

Differential Topology Solution Set #2

Select Solutions

1. Show that X compact implies that any smooth map $f : X \rightarrow Y$ is proper. Recall that a space is called compact if, for every cover $\{U_i\}$ by open sets such that

$$X = \bigcup U_i$$

there is a finite subcover. This means that there is a finite subset I of all the I such that

$$X = \bigcup_{i \in I} U_i$$

and I is a finite set.

Alternatively, you may use the definition that X is compact if and only if it is closed and bounded.

Let $Z \subset Y$ be a compact set. We need to prove that $f^{-1}(Z)$ is compact. It is sufficient to prove that $f^{-1}(Z)$ is closed and bounded. It is obviously bounded, since any subset of a compact set X is bounded (since X is). We show it is closed.

Since Z is compact, it is closed. The map $f : X \rightarrow Y$ is continuous, and so the inverse image of closed sets are closed. Therefore, $f^{-1}(Z)$ must also be closed.

2. Chapter 1, Section 3, #2
3. Chapter 1, Section 3, #4 Construct a local diffeomorphism $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that is not a diffeomorphism onto its image.

Let $f(x, y) = (e^y \cos x, e^y \sin x)$. We begin by simplifying our life and writing $f(x, y)$ in polar coordinates (r, θ) . We obtain:

$$f(x, y) = (e^y, x).$$

This function is globally defined. Clearly f is smooth (it is infinitely differentiable in all directions). We check that it is also locally invertible, with a smooth inverse.

Choose a point (x, y) . Let an open neighborhood be given by $U = \{(a, b) : x - \frac{\pi}{2} < a < x + \frac{\pi}{2}, y - 1 < b < y + 1\}$. Then clearly U contains (x, y) . The image of U under f consists of

$$V = \{(s, t) \text{ such that } e^{y-1} < s < e^{y+1} \text{ and } x - \frac{\pi}{2} < t < x + \frac{\pi}{2}\}.$$

In the neighborhood V , the inverse map is

$$f^{-1}(s, t) = (t, \ln s).$$

Note that t is the unique value mod 2π such that $x - \frac{\pi}{2} < t < x + \frac{\pi}{2}$. Notice also that $\ln s$ is always well-defined, because $s > 0$ in the image (indeed, $(0, 0)$ is not in the image of f at all). These observations imply the inverse map is well-defined. Also, f^{-1} is infinitely differentiable in both directions as well – as long as $s \neq 0$, which it is not. It follows that f is locally a diffeomorphism.

On the other hand, f is clearly not a diffeomorphism onto its image: in particular, it is not 1-1 on its image since there are many values of (e^y, x) that are equivalent if we do not restrict the domain of x . (Remember we're in polar coordinates, so $(e^y, x) = (e^y, x + 2k\pi)$ for any integer $k \in \mathbb{Z}$.)

4. Chapter 1, Section 3, #7(a).
5. Chapter 1, Section 4, #1
6. Chapter 1, Section 4, #2(a)-(b)

(a) If X is compact and Y connected, show every submersion $f : X \rightarrow Y$ is surjective.

Suppose f is a submersion that is not surjective. Let $y_0 = f(x_0)$ be a point in the image of X , and y_1 be a point not in $f(X)$. Since Y is connected, let $s(t)$ be a smooth path in Y such that $s(0) = y_0$ and $s(1) = y_1$. Since X is compact, the inverse image $f^{-1}(s(t))$ is closed in X (of course, $f(f^{-1}(s(t))) \neq s(t)$ for all t since not all of $s(t)$ lies in $f(X)$).

Let $g(t)$ be a curve in X such that $f(g(t)) = s(t)$ for $0 \leq t \leq t'$, where $f^{-1}(s(t' + \epsilon))$ is empty for small enough ϵ . We let $x' = g(t')$, and $y' = f(x')$. Then for any parametrization ϕ of Y around y' , (i.e. $\phi : U \rightarrow V$, where $U \subset \mathbb{R}^1$ open and V an open neighborhood of y' in Y), $f \circ \phi^{-1}$ is not surjective since $\phi^{-1}(s(t' + \epsilon))$ is not in the image of f , but is in the parametrization neighborhood.

But this contradicts the local submersion theorem, which says that there exist local coordinates around x' and y' such that $f(x_1, \dots, x_k) = (x_1, \dots, x_l)$, the canonical submersion, where $k \geq l$ are the dimensions of X and Y , respectively.

(b) Show that there exist no submersions of compact manifolds into Euclidean spaces.

If there were, then by part (a) there would be a surjective map from a compact set onto \mathbb{R}^n for some n . Consider the projection $\pi : \mathbb{R}^n \rightarrow \mathbb{R}^1$ to the first coordinate. Then $\pi \circ f : X \rightarrow \mathbb{R}^1$ is a smooth surjective function. Every smooth function on a compact set X has a maximum and a minimum, so $\pi \circ f$ cannot be surjective, a contradiction.

7. Chapter 1, Section 4, #3
8. Chapter 1, Section 5, #1
9. Chapter 1, Section 5, #2
10. Chapter 1, Section 5, #4

Additional problems for graduate students, or undergraduate extra credit

11. Chapter 1, Section 3, 7(b)
12. Chapter 1, Section 3, #10
13. Chapter 1, Section 4, #7
14. Chapter 1, Section 4, #12
15. Suppose that X is given by

$$X = \left\{ \begin{pmatrix} e^{i\theta_1} & 0 \\ 0 & e^{i\theta_2} \end{pmatrix} \text{ such that } \theta_i \in \mathbb{R} \right\}.$$

Show that the subset

$$X' = \left\{ \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}, \theta \in \mathbb{R} \right\}$$

is a submanifold of X . Do this by finding a smooth map $f : X \rightarrow \mathbb{C}$ and showing that there is a regular value y of f such that $X' = f^{-1}(y)$.

Hint. Think about determinants.

Let $f : X \rightarrow \mathbb{C}$ be the determinant map. In other words,

$$f\left(\begin{pmatrix} e^{i\theta_1} & 0 \\ 0 & e^{i\theta_2} \end{pmatrix}\right) = e^{i(\theta_1 + \theta_2)}.$$

Then f is a smooth map. Its image is the circle $S^1 \subset \mathbb{C}$ given by the set of $e^{i\theta}$ (elements of unit length in \mathbb{C}). Furthermore, $e^{i(\theta_1 + \theta_2)} = 1$ if and only if $i(\theta_1 + \theta_2) = 0$ or $2k\pi$ for some $k \in \mathbb{Z}$. In other words, $\theta_1 + \theta_2 = 2k\pi$, or $\theta_2 = 2k\pi - \theta_1$. But then since $e^{2k\pi - i\theta_1} = e^{-i\theta_1}$, we find that $f^{-1}(1) = X'$.

We need only show that 1 is a regular value for f . For any matrix $A \in X'$, we calculate the derivative $df_A : T_A(X) \rightarrow T_{\det A} S^1 = \mathbb{R}^1$.

Note that $T_A(X)$ is isomorphic to \mathbb{R}^2 , since the parameters θ_1 and θ_2 are real numbers. (You can also check this with any local parametrization of X at some point $A \in X'$.) Just to be explicit, I will find two curves $c_1(t)$ and $c_2(t)$ in X whose derivatives at $t = 0$ will form a basis for the tangent space at some $A \in X'$. For the sake of clarity, write an element of X as $(e^{i\theta_1}, e^{i\theta_2})$ instead of the matrix form. Let

$$c_1(t) = (e^{i(t+\theta_1)}, e^{i(t-\theta_1)}), \quad c_2(t) = (e^{i(t+\theta_1)}, e^{i(-t-\theta_1)}).$$

Notice that $c_1(t)$ and $c_2(t)$ are in X for all time. At $t = 0$, they pass through the point $A = (e^i, e^{-i}) \in X'$, as desired. We differentiate at 0, and find that

$$c_1'(0) = (ie^i, ie^{-i}) \quad c_2'(0) = (ie^i, -ie^{-i}).$$

In particular, the (real) linear span of these two vectors is any **real** linear combination of these two linearly independent vectors. Now any element B in $T_A(X)$ is of the form

$$B = ac_1'(0) + bc_2'(0),$$

where a and b are real numbers. To be even more explicit,

$$B = ((a+b)ie^i, (a-b)ie^{-i}) = \begin{pmatrix} (a+b)ie^i & 0 \\ 0 & (a-b)ie^{-i} \end{pmatrix}.$$

Now that we have identified $T_A(X)$ with a copy of \mathbb{R}^2 , it makes sense to take the derivative $df_A(B)$ in the usual way. Note that f is defined on the set of all 2×2 matrices with complex entries, so we can evaluate expressions such as $f(A + tB)$, even if $A + tB$ does not live in the copy of \mathbb{R}^2 that we just identified. The sum is occurring in the space \mathbb{C}^4 identified with $M(2, \mathbb{C})$, in which both A and B live.

For any $B \in T_A(X)$,

$$df_A(B) = \lim_{t \rightarrow 0} \frac{f(A + tB) - f(A)}{t} = \lim_{t \rightarrow 0} \frac{\det(A + tB) - 1}{t}.$$

We calculate the determinant of $A + tB$ directly, where $A = (e^i, e^{-i})$. We obtain

$$\begin{aligned} f(A + tB) &= f((e^i + t(a+b)ie^i, e^{-i} + t(a-b)ie^{-i})) \\ &= \det \begin{pmatrix} e^i + t(a+b)ie^i & 0 \\ 0 & e^{-i} + t(a-b)ie^{-i} \end{pmatrix} \\ &= 1 + t(a+b)i + t(a-b)i + t^2(a^2 - b^2). \end{aligned}$$

We now finish the calculation:

$$df_A(B) = \lim_{t \rightarrow 0} \frac{1 + t(a+b)i + t(a-b)i + t^2(a^2 - b^2) - 1}{t} = (a+b)i + (a-b)i = 2ai.$$

This is clearly nonzero if $a \neq 0$. Since the target space is one-dimension, this implies that df_A is surjective for all points $A \in X'$. It follows that 1 is a regular value, and that X' is therefore a submanifold of X .