Differential Topology Final Exam

Due Tuesday, May 10, 4:30p.m.

There are four problems on this exam. You must do all four. Undergraduates will be graded with a different standard, but the exam itself is the same.

- 1. (20 points) Chapter 1, Section 6, #9 (p. 33).
- 2. (20 points) Let $h : \mathbb{R}^1 \to S^1$ be $h(t) = (\cos nt, \sin nt)$, where n is a positive integer. Suppose that ω is any 1-form on S^1 . What is the relationship between $\int_{S^1} \omega$ and $\int_0^2 h^* \omega$? *Hint:* If you understand #6 p. 176 you will be able to prove your answer.
- 3. (30 points) Let X and Y be compact, oriented manifolds. Prove that

$$\chi(X \times Y) = \chi(X) \cdot \chi(Y).$$

In other words, the Euler characteristic of a product of manifolds is the product of their Euler characteristics.

- 4. (30 points) The *first homotopy group* or *fundamental group* of a manifold M, denoted $\pi_1(M)$ is defined as follows. Let x_0 be a point in M. Consider the set of maps
 - $\{f: S^1 \to M, \text{ f smooth, } f(1) = x_0\}, \text{ where } S^1 = \{z \in \mathbb{C} : z = e^{2i} \}.$

We say two maps f and g in this set are homotopic if there exists a smooth homotopy of maps between them that stays in the set. In other words, $f \sim g$ if there exists $F: S^1 \times I \rightarrow M$ such that F(s, 0) = f(s) and F(s, 1) = g(s) for all $s \in S^1$ and $F(1, t) = x_0$ for all $t \in I$. Then

$$\pi_1(M) = \{f: S^1 \to M, f \text{ smooth, } f(1) = x_0\} / \sim$$

(the set of maps modulo homotopy equivalence). The set $\pi_1(M)$ forms a group under concatination of maps: Let [f], [g] $\in \pi_1(M)$, then we define the product

[f] * [g] = [f * g]

to be the homotopy class of the map given by

$$f * g(e^{2i}) = \begin{cases} f(e^{2i(2)}) & \text{if } \theta \in [0, 1/2] \\ g(e^{2i(2-1)}) & \text{if } \theta \in (1/2, 1) \end{cases}$$

You can think of this new map as spending the first half of time to trace out f and the second half of time to trace out g.

Prove that \mathbb{Z} is a subgroup of $\pi_1(S^1)$. *Hint:* Try to find maps that you can prove live in different homotopy classes. Don't forget to show the group structure!!