

Math 677.
Lecture 22.

Global Theory

Def. A dynamical system on E is
a map $\varphi: \mathbb{R} \times E \rightarrow E$, $\varphi \in C^1$

s.t. $\varphi_t(x) = \varphi(t, x)$ satisfies (i) $\varphi_0(x) = x, \forall x \in E$
(ii) $\varphi_t \circ \varphi_s(x) = \varphi_{t+s}(x)$
 $\forall s, t \in \mathbb{R}, x \in E$

Ex. $\varphi(t, x) = e^{At} x$
- solution to IVP $\begin{cases} \dot{x} = Ax \\ x(0) = x_0 \end{cases}$

→ $\varphi(t, x)$ - dyn. system on $E \subset \mathbb{R}^n \Rightarrow f(x) = \frac{d}{dt} \varphi(t, x) \big|_{t=0}$
defines a C^1 -vector field on E , s.t.
 $\forall x_0 \in E$ $\varphi(t, x_0)$ - solution to IVP $\begin{cases} \dot{x} = f(x) \\ x(0) = x_0 \end{cases}$

→ $\forall x_0 \in E \Rightarrow$ max. interval of existence
for $\varphi(t, x_0)$ is $I(x_0) = (-\infty, \infty)$.

→ if $\dot{x} = f(x)$, $f \in C^1(E)$, E - open set in $\mathbb{R}^n$
 $\varphi(t, x_0)$ - sol. to IVP, $x_0 \in E$
then $\varphi(t, x)$ - dyn. system $\Leftrightarrow I(x_0) = \mathbb{R}$

Def. $f, g \in C^1(E_2)$, E_1, E_2 - open $\subset \mathbb{R}^n$
 $\overset{\uparrow}{C^1(E_1)} \quad \begin{cases} \dot{x} = f(x) \\ \dot{x} = g(x) \end{cases} \text{ top. equivalent if}$

$\exists H$ -homeo: $E_1 \xrightarrow{\text{onto}} E_2$ which maps
traj. of one system onto traj. of the other,
and preserves orientation by time.

If in addition H preserves parameterization by time, the systems are top. Conjugate.

Observation:

$$(1) \begin{cases} \dot{x} = f(x) \\ x(0) = x_0 \end{cases} \quad \underset{\substack{\sim \\ \text{top.} \\ \text{equivalent}}}{\quad} \quad \begin{cases} \dot{x} = \frac{f(x)}{1+|f(x)|} \\ x(0) = x_0 \end{cases} \quad (*)$$

Time rescaling: $\tau(t) = \int_0^t (1+|f(x(s))|) ds$
in τ , $\dot{x}(\tau) = \frac{dx}{d\tau} \cdot \frac{d\tau}{dt} = \frac{dx}{dt} / \frac{d\tau}{dt} \Rightarrow$

$$H = Id \text{ (same portrait)} \quad \dot{x}(\tau) = \frac{f(x)}{1+|f(x)|}$$

$x(t(\tau))$ is solution to $(*)$, with
 $t(\tau)$ - inverse of $\tau(t)$ given above
strictly increasing.

$$\tau(t): I_0(x(t)) \longrightarrow I_0(x(t(\tau)))$$

$$(\alpha, \beta) \longrightarrow (-\infty, \infty)$$

Can always do this as long as $f \in C^1(\mathbb{R}^n)$

Ex. 1 $\begin{cases} \dot{x} = x^2 \\ x(0) = x_0 \end{cases} \quad \exists! x(t) = \frac{x_0}{1-x_0 t}$

$$I(x_0) = \begin{cases} (-\infty, \frac{1}{x_0}), & x_0 > 0 \\ (\frac{1}{x_0}, \infty), & x_0 < 0 \\ (-\infty, \infty), & x_0 = 0 \end{cases}$$

Consider $\begin{cases} \dot{x} = \frac{f(x)}{1+|f(x)|} = \frac{x^2}{1+x^2} \\ x(0) = x_0 \end{cases}$

$$\exists! \text{ sol. } x(t) = \begin{cases} \frac{1}{2} \left(t + x_0 - \frac{1}{x_0} + \frac{x_0}{|x_0|} \sqrt{t^2 + 2(x_0 - \frac{1}{x_0})t + (x_0 + \frac{1}{x_0})^2} \right) & x_0 \neq 0 \\ 0, & x_0 = 0 \end{cases}$$

$$I(x_0) = (-\infty, \infty), \text{ if } x_0 > 0 \quad x(t) \xrightarrow[t \rightarrow \infty]{} \infty, x(t) \xrightarrow[t \rightarrow -\infty]{} 0$$

$$x_0 < 0 \quad x(t) \xrightarrow[t \rightarrow \infty]{} 0, x(t) \xrightarrow[t \rightarrow -\infty]{} -\infty$$

$$\tau(t) = t + \frac{x_0^2 t}{1 - x_0 t} = t, \quad x_0 = 0$$

maps $I(x_0)$ onto $(-\infty, \infty)$
 $\uparrow$ previous system

Ex. 2. $\begin{cases} \dot{x} = \frac{1}{2x} \\ x(0) = x_0 \end{cases}$

$$\exists! \text{ sol. } x = \sqrt{t + x_0^2}$$

$$I(x_0) = (-x_0^2, \infty)$$

$$f(x) = \frac{1}{2x} \in C^1(0, \infty)$$

If we take $\begin{cases} \dot{x} = \frac{\frac{1}{2x}}{1 + \frac{1}{2x}} = \frac{1}{2x+1} \\ x(0) = x_0 \end{cases} \quad \exists! \text{ sol.}$

$$x = -\frac{1}{2} + \sqrt{t + (x_0 + \frac{1}{2})^2}$$

$$\mathbb{R} \neq I(x_0) = (-(x_0 + \frac{1}{2})^2, \infty)$$

the trick
 does not work
 since $E = (0, \infty) \neq \mathbb{R}$

Thm 1. $f \in C^1(\mathbb{R}^n) \Rightarrow$ system (1) is top. equivalent
 to system (*). In other words, we can
 always talk about dyn. system
 when $f \in C^1$ on entire plane.
 (you can always rescale time)

Sketch of proof:

$$1) f \in C^1(\mathbb{R}^n) \Rightarrow \frac{f(x)}{1+|f(x)|} \in C^1(\mathbb{R}^n)$$

Define $x(t)$ - solution to IVP $\begin{cases} \dot{x} = \frac{f}{1+|f|} \\ x(0) = x_0 \end{cases}$

on $I(x_0) = (\alpha, \beta)$

$$\Rightarrow x(t) = x_0 + \int_0^t \frac{f(x(s))}{1+|f(x(s))|} ds \quad \forall t \in (\alpha, \beta)$$

$$\Rightarrow |x(t)| \leq |x_0| + \int_0^t ds = |x_0| + |t|, \quad \forall t \in (\alpha, \beta)$$

2) $\Rightarrow$ solutions of IVP are contained in the compact set: $\{x \in \mathbb{R}^n \mid |x(t)| \leq |x_0| + \beta\}$ in $\mathbb{R}^n$

then $\beta = \infty \Rightarrow I(x_0) = (\alpha, \infty)$ if $\beta < \infty$

3) Similarly $\alpha = -\infty \Rightarrow I(x_0) = (-\infty, \beta)$.

Thm 2. $f \in C^1(E)$, E -open $\subset \mathbb{R}^n$

$\Rightarrow \exists F \in C^1(E)$ s.t. $\dot{x} = F(x)$ dyn. system on E , top. equivalent to $\dot{x} = f(x)$ on E .

Thm 3. $f \in C^1(\mathbb{R}^n)$, global Lipschitz continuity $|f(x) - f(y)| \leq M|x - y|$, $\forall x, y \in \mathbb{R}^n$

$\Rightarrow \forall x_0 \in \mathbb{R}^n$ IVP (1) $\exists!$ sol. defined $\forall t \in \mathbb{R}$.
($I(x_0) = (-\infty, \infty)$)

Thm 4. $f \in C^1(M)$, M -compact manifold

$\Rightarrow \forall x_0 \in M \exists!$ sol. of (1).

Global stability of $\begin{cases} \dot{x} = f(x) \\ x(0) = x_0 \end{cases}$ is associated

Ex. with phenomena s.as cycles, ω -limits and periodic solutions.

$$\begin{cases} \dot{x} = f(x, \mu) \\ x(0) = x_0 \end{cases} \quad Df(x_0, \mu_0) \text{ has } \operatorname{Re}(\lambda_i) = 0 \text{ for a simple pair of eigenvalues } \lambda_i, \lambda_{i+1}$$

Implicit function theorem: $\forall \mu \sim \mu_0$

$\exists!$ equilibrium pt $x_\mu \sim x_0$.

if eigenvalues of $Df(x_\mu, \mu)$ cross $\{\operatorname{Re} \lambda = 0\}$ at $\mu = \mu_0 \Rightarrow$ dimension of W^s, W^u will change $\Rightarrow$ structurally unstable u.f. at x_0 for the bifurcation value μ_0 .

$$\begin{cases} \dot{x} = -y + x(\mu - x^2 - y^2) \\ \dot{y} = x + y(\mu - x^2 - y^2) \end{cases} \quad (0,0) - \text{crit. pt.}$$

$$Df(0, \mu) = \begin{bmatrix} \mu & -1 \\ 1 & \mu \end{bmatrix}$$

$(0,0)$ - focus:

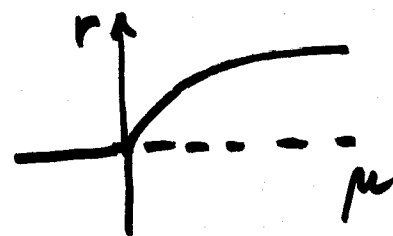
stable if $\mu < 0$

unstable if $\mu > 0$

focus or center if $\mu = 0$.

$\mu_0 = 0$: Hopf bifurcation

In polar coordinates: $\begin{cases} \dot{r} = r(\mu - r^2) \\ \dot{\theta} = 1 \end{cases}$



$$\gamma_\mu(t) = \sqrt{\mu}(\cos t, \sin t)$$

$\nwarrow$ 1-parameter family of limit cycles

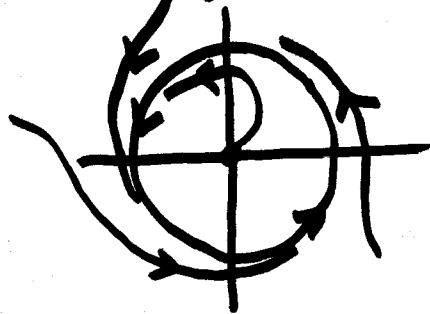
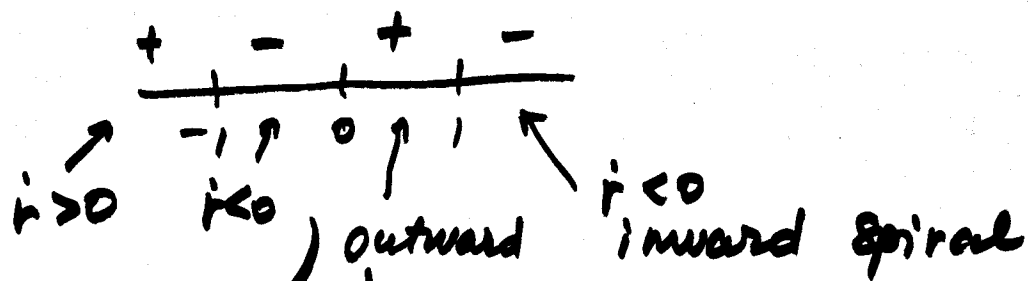
$$\begin{aligned} \lambda^2 + 1 &= 0 \\ (\mu - \lambda)^2 + 1 &= 0 \\ (\mu - \lambda)^2 &= -1 \\ \lambda &= \mu \pm \sqrt{-1} \end{aligned}$$



$\mu > 0$
 $\dot{r} = 0 \Rightarrow r^2 = \mu$
limit cycle



$$\mu=1: \begin{cases} \dot{r} = r(1-r^2) \\ \dot{\theta} = 1 \end{cases} \rightarrow \theta = t + \theta_0$$



counter clockwise spiraling
around the limit
cycle: $\Gamma = \{r=1\}$