

Math 672.
Lecture 17.

Liapunov fct $V(x,y)$:

to prove stability, necessary to have
 $V = 0$ at x_0 - crit. pt.
 $V > 0$ for all $\vec{x} \neq \vec{x}_0$

to prove unstable crit. pt. at x_0 ,
can choose V s.t.
 $V(x_0) = 0, V(\vec{x}) > 0$ for
Some $\vec{x}$ arbitrary close
to x_0 (can be
a subset of)
 $N_\delta(x_0)$)

Ex. $\begin{cases} \dot{x} = x^3 + yx^2 \\ \dot{y} = -y + x^3 \end{cases}$

Prove that $(0,0)$ -
unstable by Lyapunov
method.

$$Df = \begin{pmatrix} 0 & x^2 \\ 0 & -1 \end{pmatrix} \Big|_{(0,0)} = \begin{pmatrix} 0 & 0 \\ 0 & -1 \end{pmatrix} \text{ non-hyperbolic pt.}$$

$$V = \frac{1}{2}(x^2 - y^2) \quad \dot{V} = x \cdot \dot{x} - y \cdot \dot{y} \\ = x(x^3 + yx^2) - y(-y + x^3) \\ = x^4 + yx^3 + y^2 - yx^3 = x^4 + y^2 > 0$$

Last time: CMT for the case of $\operatorname{Re}(\lambda_i) \leq 0$

Now: general form of CMT.

Thm. (Local Central Manifold Thm)

$E \subset \mathbb{R}^n$ - open, $\{0\} \in E$, $f \in C^1(E)$, $f(0) = 0$

$$Df(0) = \text{diag} \begin{bmatrix} C & P & Q \end{bmatrix}$$

$\begin{matrix} \uparrow & \nwarrow & \searrow \\ \text{Re}(\lambda_i) = 0 & \text{Re}(\lambda_i) < 0 & \text{Re}(\lambda_i) > 0 \end{matrix}$

$\Rightarrow \exists \begin{matrix} h_1(x) \in C^1 \\ h_2(x) \in C^1 \end{matrix}$ s.t. in $N_{\delta}\{0\}$

$$\begin{cases} Dh_1 [Cx + F(x, h_1, h_2)] - Ph_1 - G(x, h_1, h_2) = 0 \\ Dh_2 [Cx + F(x, h_1, h_2)] - Qh_2 - H(x, h_1, h_2) = 0 \end{cases}$$

s.t. $\dot{x} = f(x)$ can be written in the

form
$$\begin{cases} \dot{x} = Cx + F(x, y, z) \\ \dot{y} = Py + G(x, y, z) \\ \dot{z} = Qz + H(x, y, z) \end{cases} \quad \text{top. conjugate}$$

to the system
$$\begin{cases} \dot{x} = Cx + F(x, h_1, h_2) \\ \dot{y} = Py \\ \dot{z} = Qz \end{cases} \quad \text{in } N_{\delta}\{0\}.$$

$\mathbb{R}^2$ Hyperbolic pts: nodes, saddles, foci, centers
Center-focus

Non-hyperbolic pts: $\oplus$ cusp, saddle-node,
elliptic domain

Consider $A = Df(x_0) \Rightarrow A$ has at least one
zero eigenvalue

Case 1. $\text{tr} A \neq 0$ ($\lambda_1 = 0, \lambda_2 \neq 0$)

$$\dot{x} = f(x) \sim \begin{cases} \dot{x} = p_2(x, y) \\ \dot{y} = y + q_2(x, y) \end{cases}$$

$p_2, q_2 \in C^\infty$, start with quadratic terms in expansion.

Claim 1: $\{0\}$ - isolated pt of $\dot{x} = f(x)$.
 $y = \varphi(x)$: solution to $y + q_2(x, y) = 0$ in $N_\delta(0)$.

$$\Psi = p_2(x, \varphi(x)) = a_m x^m + \dots, m \geq 2$$

- $\Rightarrow$ (1) m -odd, $a_m > 0 \Rightarrow \{0\}$ - unstable node
 (2) m -odd, $a_m < 0 \Rightarrow \{0\}$ - saddle
 $\Rightarrow$ (3) m -even $\Rightarrow \{0\}$ - saddle-node



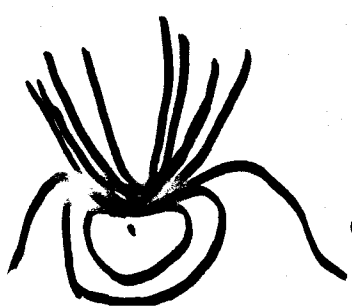
Case 2. $\text{tr} A = 0$ ($\lambda_1 = 0, \lambda_2 = 0$)

$$\dot{x} = f(x) \sim \begin{cases} \dot{x} = y \\ \dot{y} = a_k x^k [1 + h(x)] + b_n x^n y [1 + g(x)] + y^2 R(x, y) \end{cases}$$

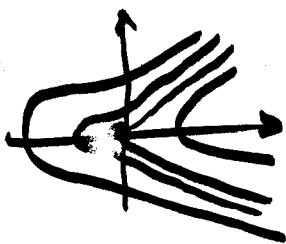
Normal form
 h, g, R - analytic
 $h(0) = g(0) = 0, k \geq 2$
 $a_k \neq 0, n \geq 1$

Claim 2: $k = 2m + 1, m \geq 1$
 $\lambda = b_n^2 + 4(m+1)a_k$

- if $a_k > 0 \Rightarrow \{0\}$ - saddle
 if $a_k < 0 \Rightarrow$ (1) $b_n = 0 \Rightarrow$ focus or center
 (2) $b_n \neq 0, n > m \Rightarrow$ focus
 $n = m, \lambda < 0 \Rightarrow$ or center
 (3) $b_n \neq 0, n$ -even, $n < m \Rightarrow$ node
 $b_n \neq 0, n$ -even, $n = m, \lambda > 0 \Rightarrow$ node
 (4) $b_n \neq 0, n$ -odd, $n < m \Rightarrow$ elliptic
 $b_n \neq 0, n$ -odd, $n = m, \lambda > 0 \Rightarrow$ domain



Claim 3: $k=2m, m \geq 1,$



if (1) $B_n = 0$
 $B_n \neq 0, n \geq m \Rightarrow \underline{\text{cusp}}$

(2) $B_n \neq 0, n < m \Rightarrow \text{saddle-node}$

Normal form theory.

$$\dot{x} = f(x)$$



$$\dot{x} = Jx + F(x)$$

x_0 -nonhyperbolic
pt

$\uparrow$ Jordan form of A

By CMT only C -part of J matters
 $(\dim C < \dim A)$
 reduced system to a
 lower-dim case

Central
Manifold Theorem

Normal form theory: reduces $\dot{x} = Jx + F(x)$
 to a system with a simple
 form of $F(x)$.

This is done by a nonlinear transformation
 $x = y + h(y), h(y) = O(|y|^2), |y| \rightarrow 0.$

This transformation is almost like identity
 close to $\{0\} \Rightarrow$ we end up with a top.
 conjugate system.