

Math 677. Fall 2009.  
Homework #1 Solutions.

**Part I.** Exercises are taken from "Differential Equations and Dynamical Systems" by Perko, 3rd edition.

**Problem Set 2: # 3**

Write the following linear DE with const coefficients in the form of the linear system  $\dot{x} = Ax$  and solve:

(a)  $\ddot{x} + \dot{x} - 2x = 0$ .

Substitution  $x_1 = x, x_2 = \dot{x}$  yields an equivalent 1st order system

$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = 2x_1 - x_2 \end{cases} \quad \text{i.e. } \dot{x} = Ax, \text{ where } A = \begin{bmatrix} 0 & 1 \\ 2 & -1 \end{bmatrix}$$

Eigenvalues  $\lambda_1 = 1, \lambda_2 = -2$ , eigenvectors  $v_1 = [1, 1]^T, v_2 = [1, -2]^T$ . Hence

$$P = \begin{bmatrix} 1 & 1 \\ 1 & -2 \end{bmatrix} \quad \text{with } P^{-1} = \begin{bmatrix} 2/3 & 1/3 \\ 1/3 & -1/3 \end{bmatrix}.$$

The solution of the IVP is given by

$$x(t) = P \begin{bmatrix} e^t & 0 \\ 0 & e^{-2t} \end{bmatrix} P^{-1} x(0).$$

**Problem Set 3: # 4**

If  $T$  is a linear transformation on  $\mathbf{R}^n$  with  $\|T - I\| < 1$ , prove that  $T$  is invertible and that the series  $\sum_{k=0}^{\infty} (I - T)^k$  converges absolutely to  $T^{-1}$ .

To show that  $T$  is invertible, notice that

$$\|Tx\| = \|(I + (T - I))x\| \geq \|x\| + \|(T - I)x\| \geq \quad (1)$$

$$\geq \|x\| - \|T - I\|\|x\| = (1 - \|T - I\|)\|x\| > 0 \quad (2)$$

for all  $\|x\| > 0$ . In other words,  $\|Tx\| = 0$  iff  $\|x\| = 0$ , a criterion of invertibility.

The absolute convergence of the series to  $T^{-1}$  follows from geometric series formula for matrices.

**Problem Set 4: # 4** Consider

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \\ 1 & 0 & -1 \end{bmatrix}$$

Eigenvalues:  $\lambda_1 = 1, \lambda_2 = -1, \lambda_3 = 2$ , eigenvectors  $v_1 = (2, -2, 1), v_2 = (0, 0, 1), v_3 = (0, 1, 0)$ .

$$P = \begin{bmatrix} 2 & 0 & 0 \\ -2 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}, \text{ and } P^{-1} = \frac{1}{2} \begin{bmatrix} 1 & 0 & 0 \\ -1 & 0 & 2 \\ 2 & 2 & 0 \end{bmatrix}$$

which leads to  $x(t) = e^{At}x(0) = P \text{diag}(\lambda_1, \lambda_2, \lambda_3) P^{-1} x(0)$ , i.e.

$$x(t) = \begin{bmatrix} e^t & 0 & 0 \\ e^{2t} - e^t & e^{2t} & 0 \\ \frac{1}{2}(e^t - e^{-t}) & 0 & e^{-t} \end{bmatrix} x(0)$$

**Problem Set 5: # 5** Second order equation  $\ddot{x} + a\dot{x} + bx = 0$  is equivalent to  $\dot{x} = Ax$  with

$$A = \begin{bmatrix} 0 & 1 \\ -b & -a \end{bmatrix}$$

Eigenvalues are given by  $\frac{1}{2}(-a \pm \sqrt{a^2 - 4b})$  and  $\lambda_1 \cdot \lambda_2 = b, \lambda_1 + \lambda_2 = -a$ . According to the standard classification of equilibria for linear systems, we have the following cases:

- (1) If  $b < 0$ , the origin is a saddle.
- (2) If  $b > 0, a = 0$ , it is a center.
- (3)  $b > 0, a^2 - 4b \geq 0$  is a stable node for  $a < 0$  and unstable node for  $a > 0$
- (4)  $b > 0, a^2 - 4b \leq 0$  is a stable focus for  $a < 0$  and unstable focus for  $a > 0$ .

**Part II.** Prove the following properties of  $e^A$ :

- (1) if  $A$  is diagonalizable, so is  $e^A$   
This follows from the fact that  $e^A = e^{P^{-1}AP} = P^{-1}e^AP$ .
- (2) if  $A$  is symmetric, then  $e^A$  is positive definite

If  $A^T = A$ , there is an orthogonal matrix  $Q$  s.t.  $A = Q^{-1}\Lambda Q$ , so that  $(e^A x, x) = (Q^T e^\Lambda Q x, x) = (e^\Lambda Q x, Q x) > 0$  for all  $x > 0$ .

(3)  $\det(e^{At}) = e^{\text{tr} A}$

If  $A = P^{-1}\Lambda P$ ,  $\det e^{At} = \prod e^{\lambda_i t}, i = 1, \dots, n$ . By the properties of trace,  $e^{\text{tr} A} = e^{\lambda_1 + \dots + \lambda_n} = \prod e^{\lambda_i t}$ . The statement follows from the observation that  $\text{tr} P^{-1}\Lambda P = P^{-1}\text{tr} \Lambda P$  and the fact that  $A = P^{-1}JP$ , where  $J$  is composed of Jordan blocks  $J_i$ , each of which satisfies the above relation.

(4)  $e^{At} = T^{-1}e^{TAT^{-1}t}T$ .

This follows from the calculation

$$T^{-1}e^{TAT^{-1}t}T = T^{-1} \sum_{k=0}^{\infty} \frac{(TAT^{-1}t)^k}{k!} = \sum_{k=0}^{\infty} \frac{A^k t^k}{k!} = e^{At}$$