

Sections covered: 1.1, 1.2, 1.3, 1.4, 1.5, 1.7, 1.8, 1.9

LEARNING OUTCOMES:

- 1- Recognize a system of linear equations
- 2- Reduce a system into echelon form using row operations
- 3- Interpret the solution(s) of a system of linear equations
- 4- Solve a system using backward substitution
- 5- Visualize a matrix-vector product $A\vec{x} = \vec{b}$ as a linear combination of the columns of A , with weights being the entries in \vec{x} .
- 6- Understand the relation between the consistency of a system and linear combinations of the columns.
- 7- Compute a matrix-vector product.
- 8- Determine if a homogeneous system has a nontrivial solution
- 9- Determine if a set is linearly independent using the solution(s) of a homogeneous system
- 10- Determine if some sets are linearly independent using shortcut rules
- 11- Determine if a homogeneous system has a nontrivial solution
- 12- Determine if a set is linearly independent using the solution(s) of a homogeneous system
- 13- Determine if some sets are linearly independent using shortcut rules

PROBLEM ONE: True or False

Mark each statement True or False. Justify each answer or give a counter example.

- a) If a set contains fewer vectors than there are entries in the vectors, then the set is linearly independent
- b) The columns of a 4×5 matrix are linearly dependent.
- c) $(AB)^T = A^T B^T$.
- d) If A is a 2×6 matrix and T is a linear transformation defined by $T(\vec{x}) = A\vec{x}$, then the domain of T is \mathbb{R}^2 .
- e) If A and B are square matrices of the same size then $AB = BA$.

PROBLEM TWO: Linear independence

- a) Use a homogeneous system to determine if the vectors $\vec{a}_1, \vec{a}_2, \vec{a}_3$ are linearly independent

$$\vec{a}_1 = \begin{bmatrix} 1 \\ 0 \\ 4 \end{bmatrix}, \vec{a}_2 = \begin{bmatrix} 2 \\ 1 \\ 5 \end{bmatrix}, \vec{a}_3 = \begin{bmatrix} 3 \\ 0 \\ 6 \end{bmatrix}$$

- b) Explain how the solution(s) of your homogeneous system determines whether the set above is linearly independent or linearly dependent.

PROBLEM THREE: Matrix of a linear transformation

Define $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T(\vec{x}) = T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} 4x_1 - x_2 \\ 2x_2 \end{bmatrix}$

- a) Let $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ be two vectors in \mathbb{R}^2 and let c be any scalar. Prove that T is a linear transformation.
- b) Find the standard matrix A of T.
- c) Is T one-to-one? Prove your answer using the matrix A.
- d) Is T onto? Prove your answer using the matrix A.

PROBLEM FOUR: Matrix Operations

Find $(AB)^T$ given that

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 0 \\ 4 & 0 & 0 \end{bmatrix} \text{ and } B = \begin{bmatrix} -1 & -2 & -3 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

PROBLEM FIVE: Solution of a system of linear equations

Find all solutions, if any exist, of the following system. If the system has multiple solutions, write the solution set as the Span of some vectors.

$$x_1 + 3x_2 - 5x_3 = 0$$

PROBLEM 6

a) Determine whether the following linear system is consistent or not but do not solve it

$$\begin{aligned}2x_2 + 2x_3 &= 0 \\x_1 - 2x_4 &= -3 \\x_3 + 3x_4 &= -4 \\-2x_1 + 3x_2 + 2x_3 + x_4 &= 5.\end{aligned}$$

b) Row reduce the following matrix to reduced echelon form and list the pivot columns

$$\begin{pmatrix} 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{pmatrix}.$$

PROBLEM 7 Determine whether or not $A\mathbf{x} = \mathbf{0}$ has any non-trivial solutions where $A = \begin{pmatrix} 1 & 2 & 5 \\ -2 & -3 & -8 \\ -1 & 1 & 1 \end{pmatrix}$.

If it does then write down the solution set.

PROBLEM 8

a) Define precisely when a set of vectors $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_p\}$ is *linearly independent*.

b) Prove that if a set of non-zero vectors is linearly dependent then one of the vectors can be written as a linear combination of the previous ones.

PROBLEM 9

a) Consider the linear transformation T that corresponds to the matrix $A = \begin{pmatrix} 1 & 3 & 9 & 2 \\ 1 & 0 & 3 & -4 \\ 0 & 1 & 2 & 3 \\ -2 & 3 & 0 & 5 \end{pmatrix}$. Find

all the vectors that are mapped into the zero vector by T . Does the range of T equal the codomain of T ?

b) If instead, A represented the augmented matrix of a linear system of equations, would it be consistent or inconsistent?

PROBLEM 10

For each of the following sets of vectors, determine which values of h make the sets linearly dependent.

a) $\left\{ \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}, \begin{pmatrix} -5 \\ 7 \\ 8 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ h \end{pmatrix} \right\}$

b) $\left\{ \begin{pmatrix} 2 \\ -4 \\ 1 \end{pmatrix}, \begin{pmatrix} -6 \\ 7 \\ -3 \end{pmatrix}, \begin{pmatrix} 8 \\ h \\ 4 \end{pmatrix} \right\}$

Problem 11:

Consider the system of equations

$$\begin{aligned}x_1 + 2x_2 - x_3 &= 5 \\2x_1 - x_2 + 3x_3 &= -5 \\-x_2 + x_3 &= 0\end{aligned}$$

1. Write the augmented matrix.
2. Write the system in vector form.
3. Write the system in matrix form $A\vec{x} = \vec{b}$ (tell us what A , \vec{x} , and \vec{b} are for the system above).
4. Is the system consistent? If yes, is the solution unique?

Problem 12:

Let a, b, c, d be real numbers. Assume $a \neq 0$ and $ad - bc \neq 0$. Find the reduced row echelon form of A where

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}.$$

Record the row operations you used and point out where you need to use the assumptions $a \neq 0$ and $ad - bc \neq 0$.

Problem 13:

Mark each statement as True or False.

1. Consider a system of equations $A\vec{x} = \vec{b}$. Let B be the reduced row echelon form (RREF) of A . If every row of B contains a pivot (or leading 1), then the system is guaranteed to have a unique solution.
2. Let A be a matrix and \vec{v} a vector. The product $A\vec{v}$ is well-defined if and only if the number of rows of A equals the number of entries of \vec{v} .
3. Let $A = [\vec{a}_1 \ \vec{a}_2 \ \vec{a}_3]$ be a matrix with columns $\vec{a}_1, \vec{a}_2, \vec{a}_3$. Suppose $\vec{a}_3 = -2\vec{a}_1 + 3\vec{a}_2$. Then the equation $A\vec{x} = \vec{0}$ has infinitely many solutions.
4. Let \vec{a}_1, \vec{a}_2 be non-zero vectors in \mathbb{R}^2 . Then $\{\vec{a}_1, \vec{a}_2\}$ is guaranteed to be linearly independent.
5. If \vec{v} is a linear combination of \vec{u}_1 and \vec{u}_2 , then

$$\text{Span}\{\vec{u}_1, \vec{u}_2, \vec{v}\} = \text{Span}\{\vec{u}_1, \vec{u}_2\}$$

6. The function

$$T \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x + y - 1 \\ x \end{bmatrix}$$

is a linear transformation.

7. Let A be the matrix of a linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$. Suppose that the columns of A span \mathbb{R}^3 . Then T is onto.

Problem 14:

Let \vec{b} be a vector in \mathbb{R}^3 with components b_1, b_2, b_3 . Consider the system of equations

$$\begin{aligned}x_1 + 2x_2 - x_3 &= b_1 \\2x_1 - x_2 + 3x_3 &= b_2 \\-x_2 + x_3 &= b_3\end{aligned}$$

1. Is the system consistent for every choice of b_1, b_2, b_3 ? Justify your answer. Determine the set of all possible values of b_1, b_2, b_3 for which the system is consistent.

- Describe the set S of all \vec{b} such that the system is consistent by expressing S as the span of a collection of vectors in \mathbb{R}^3 .
- Assuming \vec{b} belongs to S , how many free variables appear in the general solution of the original system of equations?

Problem 15:

Let A be a matrix with columns $\vec{a}_1, \dots, \vec{a}_k \in \mathbb{R}^n$. Let \vec{v} be a vector with entries v_1, \dots, v_ℓ .

- What condition must k, ℓ satisfy in order for the product $A\vec{v}$ to be defined?
- Give the formula for the product $A\vec{v}$ (assuming the condition in (a) holds).
- Calculate the product $A\vec{v}$ where

$$A = \begin{bmatrix} 1 & -2 & -1 \\ 2 & 0 & 1 \end{bmatrix}, \quad \vec{v} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$

PROBLEM 16:

For all parts of this problem, consider the following system of equations:

$$\begin{aligned} x_1 + x_3 + 2x_4 &= 6 \\ x_2 - 2x_3 + 5x_4 &= 11 \\ x_1 + 2x_2 - x_3 - 3x_4 &= -2 \end{aligned}$$

- Rewrite the above system as a matrix equation of the form $A\mathbf{x} = \mathbf{b}$, labeling A , \mathbf{x} and \mathbf{b} clearly.
- Rewrite the system as a vector equation.
- Rewrite the system as an augmented matrix.
- Perform *only* the forward phase of the row reduction algorithm, identifying any pivot positions.
- How many solutions does the original system have? Are there any solutions at all?
- Perform the backward phase of the row reduction algorithm on the echelon matrix obtained in part 4, obtaining in the end reduced row echelon form.
- Identify any free variables and write the other variables in terms of them.
- Write the solution set in parametric vector form.

PROBLEM 17:

- Determine r and s such that the solution set of the system

$$-4x + ry = 2$$

$$12x + sy = -4$$

- is empty (no solution)
- contains unique solution
- contains many solutions.

- Find the value(s) of r for which the augmented matrix represents a consistent linear system

$$\begin{bmatrix} 1 & r & 4 \\ 3 & 6 & 8 \end{bmatrix}.$$

PROBLEM 18:

- Find the general solution of the system whose augmented matrix is

$$\begin{bmatrix} 3 & -4 & 2 & 0 \\ -9 & 12 & -6 & 0 \\ -6 & 8 & -4 & 0 \end{bmatrix}.$$

- Write a system of equations equivalent to the vector equations:

(i)

$$x \begin{bmatrix} 6 \\ -1 \\ 5 \end{bmatrix} + y \begin{bmatrix} -3 \\ 4 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -7 \\ -5 \end{bmatrix}.$$

(ii)

$$x \begin{bmatrix} -2 \\ 3 \end{bmatrix} + y \begin{bmatrix} 8 \\ 5 \end{bmatrix} + z \begin{bmatrix} 1 \\ -6 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

PROBLEM 19:

- Compute the products using row-vector rule for computing Ax . If the product is undefined, explain why.

(i)

$$\begin{bmatrix} -4 & 2 \\ 1 & 6 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix}.$$

(ii)

$$\begin{bmatrix} 8 & 3 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

- Does the system

$$2x_1 - 5x_2 + 8x_3 = 0$$

$$-2x_1 - 7x_2 + x_3 = 0$$

$$4x_1 + 2x_2 + 7x_3 = 0$$

has a nontrivial solution?

- State with reason whether the vectors

(i)

$$\begin{bmatrix} 5 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 8 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 7 \end{bmatrix}$$

(ii)

$$\begin{bmatrix} 1 \\ 4 \\ 7 \end{bmatrix}, \begin{bmatrix} -2 \\ 5 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

are linearly dependent.

- Let $A = \begin{bmatrix} 1 & 0 & -2 \\ -2 & 1 & 6 \\ 3 & -2 & -5 \end{bmatrix}$, $u = \begin{bmatrix} 1 \\ 0 \\ -4 \end{bmatrix}$, and $v = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$.

Define $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ by $T(x) = Ax$. Find $T(u)$ and $T(v)$.

PROBLEM 21:

Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be a linear transformation such that

$$T(x_1, x_2) = (x_1 - 2x_2, -x_1 + 3x_2, 3x_1 - 2x_2).$$

Find x such that $T(x) = (-1, 4, 9)$.

PROBLEM 22:

Let $\mathbf{u} = \begin{bmatrix} -1 \\ 3 \\ -2 \end{bmatrix}$, $\mathbf{v} = \begin{bmatrix} 4 \\ 0 \\ -1 \end{bmatrix}$, and $\mathbf{w} = \begin{bmatrix} -3 \\ -1 \\ 2 \end{bmatrix}$. Compute the indicated vector.

1. $\mathbf{u} + 2\mathbf{v} - 4\mathbf{w}$

2. $4\mathbf{u} - 2\mathbf{v} + 4\mathbf{w}$

PROBLEM 23:

Find all scalars c , if any exist, such that the given statement is true.

1. The vector $\begin{bmatrix} c \\ -c \\ 4 \end{bmatrix}$ is a scalar multiple of the vector $\begin{bmatrix} -2 \\ 2 \\ 20 \end{bmatrix}$.

2. The vector $\begin{bmatrix} 3 \\ -2 \\ c \end{bmatrix}$ is in the span of $\begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$.

Describe all solutions of a linear system whose corresponding augmented matrix can be row reduced to the given matrix. Write the solution, if it exists, in vector parametric form.

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & 3 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 2 & 4 \end{array} \right]$$
$$\left[\begin{array}{ccccc|c} 1 & 1 & 0 & 3 & 0 & -4 \\ 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Find all solutions of the given linear system. If the solution exists, write it in vector parametric form.

$$\begin{array}{rclcl} x_1 & + & 4x_2 & - & 2x_3 & = & 4 \\ 2x_1 & + & 7x_2 & - & x_3 & = & -2 \\ 2x_1 & + & 9x_2 & - & 7x_3 & = & 1 \end{array}$$
$$\begin{array}{rclcl} x_1 & & - & 2x_3 & + & x_4 & = & 6 \\ 2x_1 & - & x_2 & + & x_3 & - & 3x_4 & = & 0 \\ 9x_1 & - & 3x_2 & - & x_3 & - & 7x_4 & = & 4 \end{array}$$

Determine whether the columns of the given matrix span \mathbb{R}^4

$$\begin{bmatrix} 1 & 0 & 1 & -1 \\ 0 & -1 & -3 & 4 \\ 1 & 0 & -1 & 2 \\ -3 & 0 & 0 & -1 \end{bmatrix}$$

Determine whether the given set of vectors is dependent or independent.

1. $\left\{ \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -4 \\ 3 \end{bmatrix} \right\}$ in \mathbb{R}^3 .

$$2. \left\{ \begin{bmatrix} 1 \\ 4 \\ -1 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 5 \\ 6 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 13 \\ 4 \\ 7 \end{bmatrix} \right\} \text{ in } \mathbb{R}^4.$$

PROBLEM 28:

Find all scalars s , if any exist, such that $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ s \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ -s \\ 0 \end{bmatrix}$ are linearly independent.

PROBLEM 29:

Show that T is a linear transformation by finding a matrix that implements the mapping. Note that x_1, x_2, \dots are not vectors but are entries in vectors.

1. $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3, T(x_1, x_2) = (2x_1 - x_2, x_1 + x_2, x_1 + 3x_2)$
2. $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3, T(x_1, x_2, x_3) = (x_1 - x_2 + 3x_3, x_1 + x_2 + x_3, x_1)$

PROBLEM 30:

1. If $T(1, 0) = (3, -1)$ and $T(0, 1) = (-2, 5)$, Find $T(4, -6)$.
2. If $T(-1, 2) = (1, 0, 0)$ and $T(2, 1) = (0, 1, 2)$, Find $T(0, 10)$.

PROBLEM 31:

Give the matrix representation of the rotation of the plane counterclockwise about the origin through an angle of

1. 30°
2. 90°
3. 135°

PROBLEM 32:

Show that the linear transformation

$$T(x, y) = \begin{bmatrix} 1 & 0 \\ 0 & r \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

1. A vertical expansion, if $r > 1$
2. A vertical expansion followed by a reflection in the x -axis if $r < -1$.