Efficient Simulation Sampling Allocation Using Multi-Fidelity Models

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SIMULATION-BASED DECISION MAKING

- Simulation provides a predictive tool for decision making when problems are intractable to analytical approaches
- This talk considers a special case known as ranking & selection
 - $x_{[1]} = \operatorname{argmax}_{i \in \{1, 2, \dots, I\}} f(x_i)$
 - Stochastic black-box objective functions, observed by running iid replications of a simulation model
- Fruitful research on simulation-based decision making
 - Efficient sampling/allocation of simulation budget, convergent fast local search, parallelization, surrogate model
 - Open-source solver ISC (<u>www.iscompass.net</u>) has been used by MITRE and the Argonne National Lab in real-world problems air traffic management and power systems applications
 - What if the full-scale simulation model runs for hours?

CAN APPROXIMATION MODELS HELP?

Full-featured model	Approximation model
High-fidelity/full-scale discrete-event simulation, agent-based model, etc.	Low-fidelity/reduced-scale simulation, analytical approximation, full-model with archived data
Complex	Simple
Accurate	Approximate
Time-consuming	Fast

MULTI-FIDELITY OPTIMIZATION METHODS

- A naïve way of multi-fidelity optimization
 - Find some most promising designs using the approximation model
 - Evaluation using high-fidelity simulations
- Most approaches use interpolation/regression to "correct" low-fidelity model
 - Autoregressive framework with kriging/Gaussian process regression (Kennedy and O'Hagan 2000)
 - Radial basis function, Polynomial chaos

• Significant challenges arise when

- Solution space is high-dimensional
- High-fidelity simulation samples have heterogeneous noise
- Quality of low-fidelity model is low
- Mixed decision variables (integer, categorical)

SIMULATION OPTIMIZATION: AN ILLUSTRATIVE EXAMPLE

Resource allocation problem in a flexible manufacturing system

- 2 product types
- 5 workstations
- Non-exponential service times
- Re-entrant manufacturing process
- Product 1 has higher priority than product 2

Optimization problem:

Decision variable

Number of machines at each workstation

Objective

Minimize Expected Total Processing Time



EXAMPLE: RESOURCE ALLOCATION PROBLEM

Decision variables: number of machines allocated to each workstation

MinimizeMinimizeSubject to $5 \le #$ of machines at each workstation ≤ 10
Total # of machines at all workstatiosn = 38

of alternatives: 780

 \rightarrow Simulation/evaluation can be time consuming \rightarrow Solution space dimension can be large

FULL SIMULATION & APPROXIMATION MODELS

Approximation using M/M/c equations, ho=0.83



Bias is non-homogeneous and can be quite large

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ORDINAL RANKINGS OF DESIGNS BY LOW-FIDELITY MODEL



Designs with similar performance are grouped together, which may potentially enhance search/optimization efficiency

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A BAYESIAN FRAMEWORK FOR MULTI-FIDELITY MODELS

 For design *i*, *i* = 1, 2, ..., *k*, we model the prior distribution of high-fidelity (*f*) prediction and *d*-dimensional low-fidelity predictions (*g*) by a Gaussian mixture model

$$- \quad \vec{h}_i = (f_i, \vec{g}_i) \sim \sum_{m=1}^M \tau_m \phi(\cdot \mid \vec{\mu}_m, \Sigma_m)$$

$$- \quad \vec{\mu}_m = (\alpha_m, \vec{\beta}_m), \Sigma_m = \begin{bmatrix} \eta_m & \Gamma_m \\ \Gamma_m^T & \Lambda_m \end{bmatrix}, \Sigma_m^{-1} = \begin{bmatrix} \upsilon_m & \Upsilon_m \\ \Upsilon_m^T & \Omega_m \end{bmatrix}$$

- f_i can only be observed with a Gaussian noise $N(0, \sigma_i^2)$
- \vec{g}_i is completely observed (negligible computing cost) - $G = (\vec{g}_1, \vec{g}_2, ..., \vec{g}_k)$
- We allocate a total of *N* high-fidelity simulation replications to designs
 - Let D_n denote the samples collected after n simulation replications
 - Let n_i be the number of simulation replications allocated to design i after n simulation replications

MODEL ESTIMATION

- We extend classical model-based clustering results to the multi-fidelity setting with stochastic observations of *f*
 - Binary hidden state random variable $z_{i,m}$ assigns design *i* to cluster *m*
 - $z_i = (z_{i,1}, ..., z_{i,M})$ follows a multinomial distribution with parameters $(\tau_1, ..., \tau_M)$
- The maximal likelihood estimate of model parameters $\theta_M = \{\tau_m, \vec{\mu}_m, \Sigma_m\}_{m=1}^M$

$$- \quad \hat{\theta}_{M}^{(n)} = \arg \max_{\theta_{M} \in \Theta_{M}} \mathcal{L}(D_{n}, G; \theta_{M})$$

- $\mathcal{L}(D_n, G; \theta_M) = \prod_{i=1}^k \left[\sum_{m=1}^M \tau_m \int_{\mathbb{R}} \prod_{l=1}^{n_i} \phi(x_{i,l} | f_i, \sigma_i^2) \phi(\vec{h}_i | \vec{\mu}_m, \Sigma_m) df_i \right]$
- The Expectation-maximization (EM) algorithm is applied to compute $\hat{\theta}_{M}^{(n)}$

MODEL ESTIMATION-CONT.

- We estimate the number of components *M* using the completely observed low-fidelity estimates *G*
- Bayesian information criterion (BIC) is used to select M

$$- BIC_M = \log \mathcal{L}_g(G; \hat{\xi}_M) - \left[\frac{(d+1)(d+2)}{2}M - 1\right]\frac{\log k}{2}$$

$$- \hat{\xi}_{M} = \arg \max_{\xi_{M} \in \Xi_{M}} \mathcal{L}_{g}(G; \xi_{M}), \text{ where } \xi_{M} = \left\{ \tau_{m}, \vec{\beta}_{m}, \Lambda_{m} \right\}_{m=1}^{M}$$

$$- \mathcal{L}_g(G;\xi_M) = \prod_{i=1}^k \left[\sum_{m=1}^M \tau_m \phi \left(\vec{g}_i | \vec{\beta}_m, = \Lambda_m \right) \right]$$

- We select the *M* from a specified interval that has the largest BIC_M



THEOREM 1: STOCHASTIC MODEL-BASED CLUSTERING

• After EM iteration *t*, the posterior probability of $\{z_{i,m} = 1\}$ conditional on D_n and given $\hat{\theta}_M^{(n,t)}$ is

$$\begin{aligned} &- \hat{z}_{i,m}^{(n,t)} = \frac{\hat{\tau}_{m}^{(n,t)} C_{i,m}^{(n,t)}}{\sum_{j=1}^{M} \hat{\tau}_{j}^{(n,t)} C_{i,j}^{(n,t)}}, \text{ where} \\ &- C_{i,m}^{(n)} \propto \sqrt{\frac{v_{i,m}^{(n,t)}}{|\Sigma_{m}^{(n,t)}|}} \exp\left\{\frac{1}{2} \left[\frac{\left(f_{i,m}^{(n,t)}\right)^{2}}{v_{m}^{(n,t)}} - \hat{v}_{m}^{(n,t)} \left(\hat{\alpha}_{m}^{(n,t)}\right)^{2} + 2\hat{\alpha}_{m}^{(n,t)} \left(\bar{g}_{i} - \hat{\beta}_{m}^{(n,t)}\right) \left(\hat{Y}_{m}^{(n,t)}\right)^{T} - \left(\bar{g}_{i} - \hat{\beta}_{m}^{(n,t)}\right) \widehat{\Omega}_{m}^{(n,t)} \left(\bar{g}_{i} - \hat{\beta}_{m}^{(n,t)}\right)^{T}\right]\right\}, \\ &- \hat{\alpha}_{m}^{(n,t)} = \frac{\sum_{i=1}^{k} \hat{z}_{i,m}^{(n,t-1)} f_{i,m}^{(n,t-1)}}{\sum_{i=1}^{k} \hat{z}_{i,m}^{(n,t-1)}}, \hat{\beta}_{m}^{(n,t)} = \frac{\sum_{i=1}^{k} \hat{z}_{i,m}^{(n,t-1)} \bar{g}_{i}}{\sum_{i=1}^{k} \hat{z}_{i,m}^{(n,t-1)}}, v_{i,m}^{(n,t)} = \frac{1}{\frac{n_{i}}{\sigma_{i}^{2}} + \hat{v}_{m}^{(n,t)}} \end{aligned}$$

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THEOREM 1: STOCHASTIC MODEL-BASED CLUSTERING

• The posterior distribution of f_i conditional on $\{z_{i,m} = 1\}$, D_n , G, and given $\hat{\theta}_M^{(n,t)}$ is normal with density function $\phi\left(f_{i,m}^{(n,t)}, v_{i,m}^{(n,t)}\right)$

$$- f_{i,m}^{(n,t)} = v_{i,m}^{(n)} \left[\frac{n_i}{\sigma_i^2} \bar{f}_i^{(n)} + \hat{v}_m^{(n,t)} \hat{\alpha}_m^{(n,t)} - \left(\bar{g}_i - \hat{\bar{\beta}}_m^{(n,t)} \right) \left(\hat{Y}_{i,m}^{(n,t)} \right)^T \right]$$

Weighted high-fidelity simulation sample mean

Weighted cluster mean

Weighted prediction using low-fidelity predictions

- The estimates of the model parameters are updated in the next EM iteration accordingly
- The above results can be extended for noisy \vec{g}_i

ASYMPTOTIC RESULTS

• Corollary 1: Suppose that design *i* is sampled infinitely often as $n \to \infty$, then

$$- \lim_{n \to \infty} \left[\frac{C_{i,m}^{(n,t)}}{\sum_{j=1}^{M} C_{i,j}^{(n,t)}} - \frac{\phi\left(\vec{h}_{i} | \hat{\mu}_{m}^{(n,t)}, \Sigma_{m}^{(n,t)}\right)}{\sum_{j=1}^{M} \phi\left(\vec{h}_{i} | \hat{\mu}_{j}^{(n,t)}, \Sigma_{j}^{(n,t)}\right)} \right] = 0 \text{ almost surely}$$

- This result is consistent with the classical model-based clustering result with $C_{i,m}^{(n,t)}$ playing the role of $\phi\left(\vec{h}_{i}|\hat{\mu}_{m}^{(n,t)}, \Sigma_{m}^{(n,t)}\right)$ when the effect of stochastic simulation noise is eliminated
- Using asymptotic results, we obtain lightweight approximations for posterior estimates that do not require EM iteration

ASYMPTOTICALLY OPTIMAL SAMPLING ALLOCATION POLICY

- Allocate $W = \{w_1, ..., w_I\}$ high-fidelity simulations to $x_1, ..., x_I$ to maximize the large deviation rate of incorrect selection event
- The large deviation rate of $P(f_i < f_j)$ when $\bar{f}_i^{(n)} > \bar{f}_j^{(n)}$ is given by

$$G_{i,j}(w_i, w_j) = \frac{\left(f_i - f_j\right)^2}{2\left(\frac{\sigma_i^2}{w_i} + \frac{\sigma_j^2}{w_j}\right)}$$

• Define an approximate large deviation rate (ALDR)

$$ALDR(W) \triangleq \min_{i \neq 1_{[n]}} G_{1_{[n]},i}\left(w_{1_{[n]}}, w_i\right), \text{ where } 1_{[n]} \triangleq \underset{i=1,\dots,I}{\operatorname{argmax}} \overline{f_i^{(n)}}$$

It can be shown that ALDR(W) converges with probability
1 to an upper bound on the large deviation rate of incorrect selection event

MULTI-FIDELITY BUDGET ALLOCATION POLICY

- Based on the clustering statistics, we define the following posterior means and variances
 - $f_i^{(n)} = f_{i,\widehat{m}_i}^{(n)}, v_i^{(n)} = v_{i,\widehat{m}_i}^{(n)}, i = 1, ..., k$, where \widehat{m}_i is the cluster with the largest clustering statistic for design i
 - Let [i] be the design index after sorting all designs in descending order posterior means, i.e., $f_{[1]}^{(n)} > \cdots > f_{[k]}^{(n)}$

- Let
$$\delta_i^{(n)} = \left(f_{[1]}^{(n)} - f_i^{(n)}\right)^2$$

 The (approximately) optimal sampling allocation policy can be obtained by solving

$$\frac{w_{[i]}}{w_{[j]}} = \frac{v_{[i]}^{(n)} \delta_{[j]}^{(n)}}{v_{[j]}^{(n)} \delta_{[i]}^{(n)}} \text{ for } i, j \neq 1, \ w_{[1]} = \sqrt{v_{[1]}^{(n)}} \sqrt{\sum_{i \neq 1} \frac{w_{[i]}^2}{v_{[i]}^{(n)}}}$$

UNDERSTANDING THE SAMPLING ALLOCATION POLICY



inversely proportional to the square of the signal to noise ratio

MACHINE ALLOCATION RESULTS

 Compare the PCS achieved by the new multi-fidelity budget allocation policy (MFBA) with optimal computing budget allocation (OCBA) for one fidelity level and equal allocation (EQ)



CRITICAL CARE FACILITY RESOURCE ALLOCATION

- Allocate 15 additional beds to four care units to reduce the number of patients denied admission because no bed is available at ICU/CCU
- The low-fidelity model is based on M/M/c equations but has poor quality due to limited buffer space and unstable systems



RESULTS

• Compare the PCS achieved by the new multi-fidelity budget allocation policy (MFBA) with OCBA EQ



CONCLUSIONS

- We present a new Bayesian framework with a Gaussian mixture model prior to utilize multi-fidelity information to improve simulation sampling efficiency for the selection of the best design
- The multi-fidelity budget allocation policy significantly improves sampling efficiency compared to a single-fidelity optimal sampling policy
- Future research includes
 - Multi-fidelity simulation optimization methods for large-scale problems
 - Incorporation of design co-variates information
 - ...
- Thank you!