

MATH 203 - EXAM 3 - SOLUTIONS

1. Let $\vec{v}_1 = \begin{bmatrix} 3 \\ 6 \\ -9 \\ -3 \end{bmatrix}$ $\vec{v}_2 = \begin{bmatrix} -1 \\ -2 \\ 3 \\ 1 \end{bmatrix}$ $\vec{v}_3 = \begin{bmatrix} 6 \\ -2 \\ 5 \\ 1 \end{bmatrix}$

Consider $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$. Since $\vec{v}_2 = -\frac{1}{3}\vec{v}_1$, we can throw out \vec{v}_2 . Since \vec{v}_3 is not a multiple of \vec{v}_1 , $\{\vec{v}_1, \vec{v}_3\}$ is a linearly independent set. Hence

$\left\{ \begin{bmatrix} 3 \\ 6 \\ -9 \\ -3 \end{bmatrix}, \begin{bmatrix} 6 \\ -2 \\ 5 \\ 1 \end{bmatrix} \right\}$ is a basis for S and $\dim(S) = 2$.

2. $\begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 2 & 3 & -1 \\ -3 & 6 & -1 & 1 & -7 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 2 & 3 & -1 \\ 0 & 0 & 5 & 10 & -10 \\ 0 & 0 & 1 & 2 & -2 \end{bmatrix}$

$\sim \begin{bmatrix} 1 & -2 & 2 & 3 & -1 \\ 0 & 0 & 1 & 2 & -2 \\ 0 & 0 & 1 & 2 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 2 & 3 & -1 \\ 0 & 0 & 1 & 2 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

(a) $\text{rank}(A) = \dim \text{Col}(A) = 2$ since A has 2 pivot columns

$\dim \text{Nul}(A) = 3$ since $\text{rank}(A) + \dim \text{Nul}(A) = 5$

(b) Basis for $\text{Col}(A) = \left\{ \begin{bmatrix} -3 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 5 \end{bmatrix} \right\} //$

Basis for $\text{Row}(A) = \left\{ \begin{bmatrix} 1 \\ -2 \\ 3 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \\ -2 \end{bmatrix} \right\} //$

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3. Let $\mathcal{E} = \{1, t, t^2\}$ the standard basis for \mathbb{P}_2 .

$$\text{Then } [t^2+1]_{\mathcal{E}} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \quad [1-t^2]_{\mathcal{E}} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \quad [1+t]_{\mathcal{E}} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & -2 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

This matrix has a pivot in every row & column.
Hence its columns form a basis for \mathbb{P}_2 . Hence \mathcal{B} forms a basis for \mathbb{P}_2 . //

$$4. (a) \quad P_{\mathcal{E} \leftarrow \mathcal{D}} = \begin{bmatrix} [1]_{\mathcal{E}} & [5]_{\mathcal{E}} \\ [-2]_{\mathcal{E}} & [-6]_{\mathcal{E}} \end{bmatrix} = \begin{bmatrix} 1 & 5 \\ -2 & -6 \end{bmatrix}$$

$$P_{\mathcal{E} \leftarrow \mathcal{C}} = \begin{bmatrix} [3]_{\mathcal{E}} & [-1]_{\mathcal{E}} \\ [-2]_{\mathcal{E}} & [0]_{\mathcal{E}} \end{bmatrix} = \begin{bmatrix} 3 & -1 \\ -2 & 0 \end{bmatrix}$$

$$(b) \quad P_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{bmatrix} [1]_{\mathcal{C}} & [5]_{\mathcal{C}} \\ [-2]_{\mathcal{C}} & [-6]_{\mathcal{C}} \end{bmatrix}$$

$$\text{If } \vec{x} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}_{\mathcal{C}} \text{ then } \begin{bmatrix} 1 \\ -2 \end{bmatrix}_{\mathcal{E}} = P_{\mathcal{E} \leftarrow \mathcal{C}} \vec{x} = \begin{bmatrix} 3 & -1 \\ -2 & 0 \end{bmatrix} \vec{x}$$

$$\text{Solving: } \vec{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\text{If } \vec{y} = \begin{bmatrix} 5 \\ -6 \end{bmatrix}_{\mathcal{C}} \text{ then } \begin{bmatrix} 5 \\ -6 \end{bmatrix}_{\mathcal{E}} = \begin{bmatrix} 3 & -1 \\ -2 & 0 \end{bmatrix} \vec{y} \quad \text{solving: } \vec{y} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$\therefore P_{C \leftarrow B} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} //$$

$$P_{B \leftarrow C} = P_{C \leftarrow B}^{-1} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}^{-1} = \frac{1}{2} \begin{bmatrix} 4 & -3 \\ -2 & 1 \end{bmatrix} //$$

5. Eigenspace for $\lambda=2 = \text{Nul}(A-2I)$

$$A-2I = \begin{bmatrix} -2 & -4 & -6 \\ -1 & -2 & -3 \\ 1 & 2 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 \\ -1 & -2 & -3 \\ -2 & -4 & -6 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\therefore (A-2I)\vec{x} = 0 \Rightarrow$$

$$x_1 = -2x_2 - 3x_3$$

x_2 free

x_3 free

$$\vec{x} = \begin{bmatrix} -2x_2 - 3x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{Basis for Eigenspace} = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix} \right\} //$$