

Math 493: Homework 2 – Anderson – Summer 2008

DUE: THURSDAY, JUNE 5, 2008

1. Consider the one dimensional heat equation

$$\begin{aligned}\frac{\partial u}{\partial t} &= \frac{\partial^2 u}{\partial x^2}, \\ u &= 0 \quad \text{on } x = 0, 1, \\ u &= f(x) \quad \text{on } t = 0,\end{aligned}$$

We shall be interested in the solution to this problem for $0 \leq x \leq 1$ and $0 \leq t \leq 1$. We shall also consider $f(x) = \sin \pi x$ where this problem has exact solution $u = \Phi(x, t) = e^{-\pi^2 t} \sin(\pi x)$.

Consider a numerical solution approach to this problem using the spatial discretization $x_j = (j - 1)/N$ for $j = 1, \dots, N + 1$ where N is the number of space intervals on $x \in [0, 1]$ and the time discretization $t_i = (i - 1)/M$ for $i = 1, \dots, M + 1$ where M is the number of time intervals on $t \in [0, 1]$. Here the grid spacings in the x and t directions are $h = 1/N$ and $k = 1/M$. Define $r = k/h^2$. Noting that $\phi_1^i = \phi_{N+1}^i = 0$ for all i define a solution vector $\vec{\phi}^i = (\phi_2^i, \phi_3^i, \dots, \phi_N^i)$ which approximates the true solution at the spatial grid points at time step i .

(a) Specifically, write a Matlab code (or perhaps three Matlab codes) to solve this problem numerically using:

1. Forward Euler Scheme

$$\vec{\phi}^{i+1} = A_{FE} \vec{\phi}^i, \tag{1}$$

where $A_{FE} = I + rT_{N-1}$.

2. Backward Euler Scheme

$$A_{BE} \vec{\phi}^{i+1} = \vec{\phi}^i, \tag{2}$$

where $A_{BE} = I - rT_{N-1}$.

3. Crank-Nicolson Scheme

$$A_{CN} \vec{\phi}^{i+1} = B_{CN} \vec{\phi}^i, \tag{3}$$

where $A_{CN} = 2I - rT_{N-1}$ and $B_{CN} = 2I + rT_{N-1}$.

In all of these cases I is an $N - 1 \times N - 1$ identity matrix and T_{N-1} is an $N - 1 \times N - 1$ tridiagonal matrices with -2 on the main diagonal and 1 on the first upper and first lower diagonals.

Your code should implement each of the above three schemes. The goal is to explore the basic properties of these schemes. Your code need not be optimized for speed and efficiency although you will probably notice things slowing down as the grids in space and time are refined so any efficiency you can include will probably pay off. You can use Matlab's built in commands to solve linear systems. Please avoid computing matrix inverses explicitly (i.e. don't use 'inv(A)').

The following questions ask you to use your Matlab code to explore issues such as error and stability. To treat the error, define an exact solution vector $\vec{\Phi}^i$ at the final time $t = 1$ that has components $\Phi(x_j, t_i)$ for $j = 2, \dots, N$. Define a relative error as

$$e = \|\vec{\phi}^i - \vec{\Phi}^i\|_2 / \|\vec{\Phi}^i\|_2$$

Note that these norms can be computed in Matlab using the `norm` command.

(b) Take $N = 20$. For Forward Euler, what is the minimum value of M required for numerical stability as predicted from theory?

(c) Take $N = 20$. Using $M = 25, 50, 100, 200, 400, 800, 1600, 3200$ examine a plot of the solution approximation at $t = 1$ – for all three methods – and discuss the results (Do not turn in every plot but you might turn in a couple representative ones). How do the results compare with the prediction in (b)? As you are doing this, make a table showing M , r and errors e_{FE} , e_{BE} and e_{CN} for each scheme. Can you observe the predicted order of accuracy in time for each of these schemes in this data? How might the value of N influence your observations?

(d) Take $N = 100$ and repeat the above calculations with $M = 25, 50, 100, 200, 400, 800$. Can you observe the predicted order of accuracy in time for each of these schemes in this data?

(e) If $N = 1000$ what is the minimum value of M required in theory to avoid numerical stability for Forward Euler? Try running a few values of M here (e.g. $M = 25, 50, 100$) and see if you can observe the second order accuracy trend in time in the Crank-Nicolson scheme. Discuss the results.

2. Derive a second-order accurate finite difference formula for

$$\left(\frac{\partial^3 u}{\partial x^3}\right)_j$$

using grid points out to $j + 2$ and $j - 2$. Suggestion: Think through your plan of attack before attempting too much algebra for this problem. Make sure you include enough terms in your Taylor expansions but try to avoid retaining more than you need.