

## 1.4. The Matrix Equation $Ax = b$

A fundamental idea in linear algebra is to view a linear combination of vectors as the product of a matrix and a vector.

Definition. If  $\underline{A}$  is an  $m \times n$  matrix, with columns  $\bar{a}_1, \dots, \bar{a}_n$ , and if  $\bar{x}$  is in  $\mathbb{R}^n$ , then the product of  $\underline{A}$  and  $\bar{x}$ , denoted by  $\underline{A}\bar{x}$ , is the linear combination of the columns of  $\underline{A}$  using the corresponding entries in  $\bar{x}$  as weights:

$$\underline{A}\bar{x} = [\bar{a}_1 \dots \bar{a}_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 \bar{a}_1 + \dots + x_n \bar{a}_n.$$

Ex.  $\begin{array}{c} 2 \times 3 \\ 3 \times 1 \end{array}$   $\begin{bmatrix} 1 & 2 & -1 \\ 0 & -5 & 3 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \\ 7 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 2 \\ -5 \end{bmatrix} + 7 \begin{bmatrix} -1 \\ 3 \end{bmatrix} =$   
 $= \begin{bmatrix} 4 \\ 0 \end{bmatrix} + \begin{bmatrix} 6 \\ -15 \end{bmatrix} + \begin{bmatrix} -7 \\ 21 \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \end{bmatrix}$

Ex. For vectors  $\bar{v}_1, \bar{v}_2, \bar{v}_3$  in  $\mathbb{R}^m$ , write the linear combination  $3\bar{v}_1 - 5\bar{v}_2 + 7\bar{v}_3$  as a matrix times a vector.

$$3\bar{v}_1 - 5\bar{v}_2 + 7\bar{v}_3 = [\bar{v}_1 \bar{v}_2 \bar{v}_3] \begin{bmatrix} 3 \\ -5 \\ 7 \end{bmatrix}$$

This approach enables us to write a system of linear equations as a matrix equation.

Namely,

$$\begin{aligned}x_1 + 2x_2 - x_3 &= 4 \\-5x_2 + 3x_3 &= 1\end{aligned}$$

can be written as

$$\begin{bmatrix} 1 & 2 & -1 \\ 0 & -5 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

Theorem. If  $A$  is a  $m \times n$ -matrix, with columns  $\bar{a}_1, \dots, \bar{a}_n$ , and if  $\bar{b}$  is a vector in  $\mathbb{R}^m$ , the matrix equation

$$A\bar{x} = \bar{b}$$

has the same solution set as the vector equation

$$x_1 \bar{a}_1 + x_2 \bar{a}_2 + \dots + x_n \bar{a}_n = \bar{b}$$

which, in turn, has the same solution set as the system of linear equations whose augmented matrix is

$$[\bar{a}_1 \ \bar{a}_2 \ \dots \ \bar{a}_n \ \bar{b}].$$

### Existence of Solutions

Theorem. The equation  $A\bar{x} = \bar{b}$  has a solution if and only if  $\bar{b}$  is a linear combination of the columns of  $A$ .

Ex. Let  $A = \begin{bmatrix} 1 & 3 & 4 \\ -4 & 2 & -6 \\ -3 & -2 & -7 \end{bmatrix}$  and  $\bar{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$ .

Does the equation  $A\bar{x} = \bar{b}$  have a solution for all possible  $b_1, b_2, b_3$ ?

Solution. Row reduce the augmented matrix for  $A\bar{x} = \bar{b}$ :

$$\left[ \begin{array}{ccc|c} 1 & 3 & 4 & b_1 \\ -4 & 2 & -6 & b_2 \\ -3 & -2 & -7 & b_3 \end{array} \right] \sim \left[ \begin{array}{ccc|c} 1 & 3 & 4 & b_1 \\ 0 & 14 & 10 & b_2 + 4b_1 \\ 0 & 7 & 5 & b_3 + 3b_1 \end{array} \right] \sim \left[ \begin{array}{ccc|c} 1 & 3 & 4 & b_1 \\ 0 & 14 & 10 & b_2 + 4b_1 \\ 0 & 0 & b_3 + 3b_1 - \frac{1}{2}(b_2 + 4b_1) & 0 \end{array} \right]$$

Hence  $A\bar{x} = \bar{b}$  has no solution if and only if  $b_3 + 3b_1 - \frac{1}{2}(b_2 + 4b_1) \neq 0$ .

In the next theorem, the sentence "The columns of A span  $R^m$ " means that every  $\bar{b}$  in  $R^m$  is a linear combination of the columns of A.

In general, a set of vectors  $\{\bar{v}_1, \dots, \bar{v}_p\}$  in  $R^m$  spans (or generates)  $R^n$ , if span  $\{\bar{v}_1, \dots, \bar{v}_p\} = R^m$ .

Theorem 4. Let A be an  $m \times n$ -matrix. The following statements are logically equivalent.

- For each  $\bar{b}$  in  $R^m$ , the equation  $A\bar{x} = \bar{b}$  has a solution.
- Each  $\bar{b}$  in  $R^m$  is a linear combination of the columns of A.
- The columns of A span  $R^m$ .
- A has a pivot position in every row.

## Computation of $A\bar{x}$

Row-Vector Rule. If the product  $A\bar{x}$  is defined then the  $i$ th entry in  $A\bar{x}$  is the sum of the products of corresponding entries from row  $i$  of  $A$  and from the vector  $\bar{x}$ .

Ex. 
$$\begin{bmatrix} 2 & -3 \\ 8 & 0 \\ -5 & 2 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ 7 \end{bmatrix} = \begin{bmatrix} 2 \cdot 4 + (-3) \cdot 7 \\ 8 \cdot 4 + 0 \cdot 7 \\ (-5) \cdot 4 + 2 \cdot 7 \end{bmatrix} = \begin{bmatrix} -13 \\ 32 \\ -6 \end{bmatrix}.$$

## Properties of the Matrix-Vector Product $A\bar{x}$

If  $A$  is an  $m \times n$  matrix,  $\bar{u}$  and  $\bar{v}$  are vectors in  $R^n$ , and  $c$  is a scalar, then

- (a)  $A(\bar{u} + \bar{v}) = A\bar{u} + A\bar{v}$
- (b)  $A(c\bar{u}) = cA\bar{u}$ .

Proof. For simplicity, take  $n = 3$ :

$$A = [\bar{a}_1 \ \bar{a}_2 \ \bar{a}_3], \quad \bar{u}, \bar{v} \in R^3$$

If  $\bar{u} = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}, \quad \bar{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$  then

$$A(\bar{u} + \bar{v}) = [\bar{a}_1 \ \bar{a}_2 \ \bar{a}_3] \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \\ u_3 + v_3 \end{bmatrix} =$$

$$= (u_1 + v_1)\bar{a}_1 + (u_2 + v_2)\bar{a}_2 + (u_3 + v_3)\bar{a}_3 =$$

$$= (u_1\bar{a}_1 + u_2\bar{a}_2 + u_3\bar{a}_3) + (v_1\bar{a}_1 + v_2\bar{a}_2 + v_3\bar{a}_3) =$$

$$= A\bar{u} + A\bar{v}.$$

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$$\text{Similarly, } A(c\bar{u}) = [\bar{a}_1, \bar{a}_2, \bar{a}_3] \begin{bmatrix} cu_1 \\ cu_2 \\ cu_3 \end{bmatrix} =$$

$$= (cu_1)\bar{a}_1 + (cu_2)\bar{a}_2 + (cu_3)\bar{a}_3 =$$

$$= c(u_1\bar{a}_1 + u_2\bar{a}_2 + u_3\bar{a}_3) = cA\bar{u}.$$