

Math 214.
Lecture 22.

Linear systems: $\vec{x}' = A\vec{x} + g$

Required: $\vec{x}' = A\vec{x}$ (*)

↑ const coeff linear
homogeneous system of ODEs.

We know: if $\vec{x}^{(1)}, \vec{x}^{(2)}$ - solutions to (*)
and $W(\vec{x}^{(1)}, \vec{x}^{(2)}) \neq 0$ then
 $\vec{x}^{(1)}, \vec{x}^{(2)}$ - form a fundam. set, i.e.

$\vec{x}(t) = c_1 \vec{x}^{(1)}(t) + c_2 \vec{x}^{(2)}(t)$ is
the general solution to (*).

Suppose $\vec{x}' = A\vec{x}$ is your system

Take $x = \xi e^{rt}$ - one solution of $x' = Ax$
↑ const vector

$$\begin{aligned} \text{Plug into } \begin{cases} x' = \xi \cdot r e^{rt} \\ x' = Ax \end{cases} & \Rightarrow \begin{cases} Ax = A(\xi e^{rt}) = e^{rt} \cdot A\xi \\ r\xi e^{rt} = A\xi e^{rt} \end{cases} \\ & \Rightarrow \boxed{r\xi = A\xi} \end{aligned}$$

So for $x = \xi e^{rt}$ to be a solution to (*),
it has to satisfy $A\xi = r\xi$.

r - eigenvalue
 ξ - eigenvector of A .

Case 1. Suppose A is a 2×2 matrix with
eigenvalues r_1, r_2
 ξ_1, ξ_2 - corresp. eigenvectors

→ $\boxed{r_1 \neq r_2, \text{ real}}$

$$\begin{aligned} \text{Then } \left. \begin{aligned} x^{(1)} &= \xi_1 e^{r_1 t} \\ x^{(2)} &= \xi_2 e^{r_2 t} \end{aligned} \right\} & \Rightarrow W(x^{(1)}, x^{(2)}) \neq 0 \end{aligned}$$

So in this case

Gen. sol. of $x' = Ax$: $x(t) = C_1 \xi_1 e^{r_1 t} + C_2 \xi_2 e^{r_2 t}$

Ex. $x' = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix} x$ $A = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix}$

Find gen. solution.

1) Find eig. values: $\det(A - rI) = 0$

$$\begin{vmatrix} 1-r & 1 \\ 4 & 1-r \end{vmatrix} = (1-r)(1-r) - 4 = 1 - 2r + r^2 - 4 = r^2 - 2r - 3 = 0$$

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

$$(r-3)(r+1) = 0$$

$$r_1 = 3 \quad r_2 = -1$$

eig. values

2) Find eig. vectors

Solve system: $(A - rI) \vec{\xi} = 0$

eig. vector corresp to r

for $r_1 = 3$: $\begin{pmatrix} 1-3 & 1 \\ 4 & 1-3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{matrix} -2v_1 + v_2 = 0 \\ 4v_1 - 2v_2 = 0 \end{matrix}$

$$\vec{\xi}_1 = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$

$$\boxed{\xi_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}}$$

$$\boxed{v_2 = 2v_1}$$

$$v_1 = 1 \Rightarrow v_2 = 2$$

for $r_2 = -1$: $\begin{pmatrix} 1-(-1) & 1 \\ 4 & 1-(-1) \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{matrix} 2v_1 + v_2 = 0 \\ 4v_1 + 2v_2 = 0 \end{matrix}$

$$\boxed{\xi_2 = \begin{pmatrix} 1 \\ -2 \end{pmatrix}}$$

$$\boxed{v_2 = -2v_1}$$

Gen. solution: $x(t) = C_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{3t} + C_2 \begin{pmatrix} 1 \\ -2 \end{pmatrix} e^{-t}$

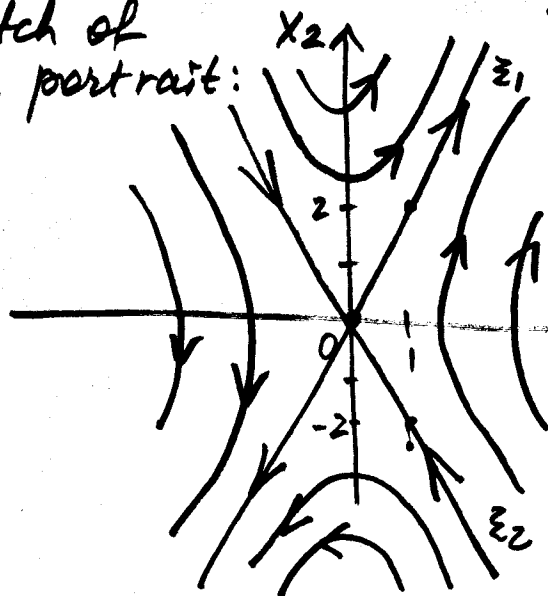
For phase portrait:

$$\lim_{t \rightarrow +\infty} x(t) = \lim_{t \rightarrow +\infty} \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{3t} \rightarrow x(t) \text{ is parallel to } \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

e^{-t} part vanishes

At $t \rightarrow -\infty \Rightarrow x(t)$ will be parallel to $\begin{pmatrix} 1 \\ -2 \end{pmatrix}$
 e^{3t} part vanishes

Sketch of phase portrait:



r_1, r_2 - different sign

$$r_1 \cdot r_2 < 0$$

$\Rightarrow$ always produces similar picture

Saddle **unstable**

Critical point at $(0,0)$.



Ex. 2

$$x' = \begin{pmatrix} 2 & -2 \\ 3 & -4 \end{pmatrix} x$$

$$\begin{vmatrix} 1-r & -2 \\ 3 & -4-r \end{vmatrix} = -4 - r + 4r + r^2 + 6 = 0$$

$$r^2 + 3r + 2 = 0$$

$$(r+2)(r+1) = 0 \quad r_1 = -2 \quad r_2 = -1$$

For ξ_1 :

$$\begin{pmatrix} 3 & -2 \\ 3 & -2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$3v_1 - 2v_2 = 0 \quad \xi_1 = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

$$v_1 = \frac{2}{3}v_2$$

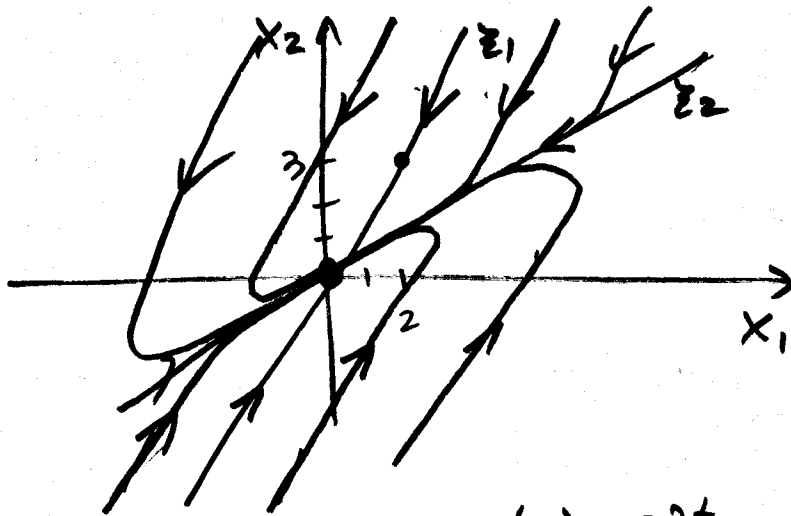
$$\xi_2: \begin{pmatrix} 2 & -2 \\ 3 & -3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow$$

$$2v_1 - 2v_2 = 0$$

$$v_1 = v_2$$

$$\xi_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Stable node
 $r_1, r_2 < 0$ real $r_1 \neq r_2$



stable node

$$r_1, r_2 < 0 \quad r_1 \neq r_2 \text{ real.}$$

Gen. sol. : $x(t) = C_1 \begin{pmatrix} 2 \\ 3 \end{pmatrix} e^{-2t} + C_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-t}$

At $t \rightarrow \infty$ $x(t) \parallel \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ Since e^{-2t} is dominated by e^{-t} , $t > 0$.

At $t \rightarrow -\infty$ $x(t) \parallel \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ Since e^{-2t} dominates e^{-t} at $t < 0$.

Classification of critical pts of $x' = Ax$.

Case 1. $r_1 \neq r_2$, real

 (a) $r_1, r_2 > 0 \Rightarrow$ unstable node at $(0,0)$.
all trajectories are repelled from 0.

 (b) $r_1, r_2 < 0 \Rightarrow$ asymptotically stable node at $(0,0)$.
all traj. are attracted to 0.

 (c) $r_1 \cdot r_2 < 0$ $\Rightarrow$ unstable saddle.
(different signs) the traj. are first attracted then repelled unless it coincides with an eigenvector (called separatrix).

Case 2. r_1, r_2 - complex.

$$r_{1,2} = \lambda \pm i\mu \Rightarrow \text{spiral}$$

$$\lambda > 0 \Rightarrow \text{unstable spiral}$$



$$\lambda < 0$$

Stable spiral



Case 3. $r_1 = r_2$ real degenerate node

$r_1, r_2 < 0 \Rightarrow$ stable

$r_1, r_2 > 0 \Rightarrow$ unstable.



Ex. $x' = \begin{pmatrix} 2 & -1 \\ 3 & -2 \end{pmatrix} x$

Find gen. sol.

and sketch phase portrait

$$r_1 = 1 \quad r_2 = -1$$
$$\xi_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \xi_2 = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

