11.1 Definition of the Integral.

A. Integration on the line.

1. <u>Definition 1.</u> A partition *P* of an interval [*a*, *b*] is a finite set $P = \{x_0, x_1, ..., x_n\}$ where $a = x_0 < x_1 < \cdots < x_n = b$. Given a bounded function *f* defined on [*a*, *b*], define $M = \sup\{f(x): x \in [x_1, ..., x_n]\}$

 $M_k = \sup\{f(x): x \in [x_{k-1}, x_k]\},\$

and

$$m_k = \inf\{ f(x): x \in [x_{k-1}, x_k] \}.$$

Define the *upper and lower sums* of f by

$$U(f,P) = \sum_{\substack{k=1 \ n}}^{n} M_k (x_k - x_{k-1})$$
$$L(f,P) = \sum_{\substack{k=1 \ k=1}}^{n} m_k (x_k - x_{k-1})$$

lf

$$\sup_{P} L(f, P) = \inf_{P} U(f, P).$$

then $\int_{a}^{b} f(x) dx$ is this common number and f is said to be *Riemann integrable on* [a, b] or $f \in \mathcal{R}[a, b]$.

- B. Integration on \mathbb{E}^n .
 - 1. What replaces the interval [*a*, *b*]?

<u>Definition 2</u>. A *closed rectangular block* (or just a *rectangle*) $B = [a, b] \subseteq \mathbb{E}^n$ is defined by $B = [a, b] = [a_1, b_1] \times \cdots \times [a_n, b_n]$ 2. What replaces a partition?

<u>Definition</u> 3. Given a rectangle [a, b] in \mathbb{E}^n , a *partition* \mathcal{P} of [a, b] is the Cartesian product $\mathcal{P} = P_1 \times \cdots \times P_n$ where each P_i is a partition of $[a_i, b_i]$. A *grid* is a collection of rectangles of the form $I_1 \times \cdots \times I_n$ where each I_j is a subinterval of the partition P_j , that is, $I_j = [x_{k-1}^j, x_k^j]$. 3. We also need to specify the notion of volume.

<u>Definition</u> 4. Let $S \subseteq \mathbb{E}^n$ and suppose that $S \subseteq B$ for some rectangle *B*. Let \mathcal{P} be a grid on *B*, and define

$$V(S,\mathcal{P}) = \sum_{\substack{B_j \in \mathcal{P} \\ B_j \cap \bar{S} \neq \emptyset}} vol(B_j);$$
$$v(S,\mathcal{P}) = \sum_{\substack{B_j \in \mathcal{P} \\ B_j \subseteq S^\circ}} vol(B_j)$$

where \overline{S} is the closure and S° the interior of S.

The *inner volume* of S is $vol(S) = \sup\{v(S, \mathcal{P}): \mathcal{P} \ a \ grid \ on B\}$ and the *outer volume* is $Vol(S) = \inf\{V(S, \mathcal{P}): \mathcal{P} \ a \ grid \ on B\}$ If vol(S) = Vol(S) then S is called a *Jordan*

region and the common value is the *volume* or *Jordan content* of *S* and is denoted v(S).

4. <u>Theorem</u>. A bounded set $S \subseteq \mathbb{E}^n$ is a Jordan region if and only if $Vol(\partial S) = 0$ where $\partial S = \overline{S} \setminus S^\circ$ is the boundary of *S*.

Such a set is called a Jordan null set.

- C. Integration over Jordan Regions.
 - 1. <u>Definition</u> 5. Let $S \subseteq \mathbb{E}^n$ be a Jordan region, $f: S \to \mathbb{E}^1$ be bounded, and suppose that $S \subseteq B$ for some rectangle *B*. Extend *f* to a function on *B* by letting f(x) = 0 if $x \in B \setminus S$.

The *upper sum* of f with respect to a grid \mathcal{P} of B is

$$U(f,\mathcal{P}) = \sum_{\substack{B_j \in \mathcal{P} \\ B_i \cap E \neq \emptyset}} M_j \, \nu(B_j)$$

where $M_j = \sup\{f(\mathbf{x}): \mathbf{x} \in B_j\}$ and the *lower* sum by

$$L(f, \mathcal{P}) = \sum_{\substack{B_j \in \mathcal{P} \\ B_i \cap E \neq \emptyset}} m_j \, \nu(B_j)$$

where $m_j = \inf\{f(\mathbf{x}): \mathbf{x} \in B_j\}.$

2. <u>Definition</u> 6. The upper and lower integrals of *f* over *S* are given by

$$\overline{\int_{S} f} = \sup\{L(f, \mathcal{P}): \mathcal{P} \text{ a grid on } B\}$$

and

$$\int_{S} f = \inf\{U(f, \mathcal{P}): \mathcal{P} \text{ a grid on } B\}$$

if $\overline{\int_S f} = \underline{\int_S f}$ then the common value is the Riemann integral of f on S and is denoted $\int_S f$.

- 3. Remark.
 - a. The value of the integral over *S* is independent of the choice of rectangle *B* containing *S*.
 - b. What is the point of defining the integral this way, i.e., by enclosing *S* in a rectangle?