

Final Exam 12/13 1³⁰ - 4¹⁵

Review Session Monday 12/12 12³⁰ - 2³⁰

Room TBA (check website).

Quiz 14 7.1, 7.3.

7.5 Homogeneous Linear Systems with Constant Coefficients

Solving

$$\vec{x}' = A \vec{x} \quad A = n \times n \text{ constant matrix}$$

1. Look for solutions of the form

$$\vec{x} = \vec{z} e^{rt} \quad \vec{z} = \text{same constant vector.}$$

$$\vec{x}' = \vec{z} r e^{rt} \rightarrow \vec{z} r e^{rt} = A \vec{z} e^{rt}$$

$\vec{z}$ must satisfy $A \vec{z} = r \vec{z} \leftarrow r \text{ is an eigenvalue}$
and $\vec{z}$ an eigenvector of A .

Procedure:

(a) Find eigenvalues of A and all corresponding eigenvectors. Two possibilities;

1) Find n distinct eigenvalues and hence always n distinct eigenvectors. These eigenvectors are always linearly independent.

The eigenvalues may be complex.

2) Fewer than n distinct eigenvalues, i.e. repeated roots.

(We will look at case 1) only.)

(b) Eigen values are $\lambda_1, \lambda_2, \dots, \lambda_n$ with corresponding eigenvectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$

The general solution is:

$$\vec{x}(t) = c_1 \vec{v}_1 e^{\lambda_1 t} + c_2 \vec{v}_2 e^{\lambda_2 t} + \dots + c_n \vec{v}_n e^{\lambda_n t}$$

(c) What about Wronskian?

$$W[\vec{z}^{(1)} e^{r_1 t}, \dots, \vec{z}^{(n)} e^{r_n t}]$$

$$= \begin{vmatrix} | & | & | & | \\ \vec{z}^{(1)} e^{r_1 t} & \vec{z}^{(2)} e^{r_2 t} & \dots & \vec{z}^{(n)} e^{r_n t} \\ | & | & | & | \end{vmatrix}$$

$$= \underbrace{e^{r_1 t} e^{r_2 t} \dots e^{r_n t}}_{\text{never zero for any } t.} \begin{vmatrix} | & | & | \\ \vec{z}^{(1)} & \vec{z}^{(2)} & \dots & \vec{z}^{(n)} \\ | & | & | \end{vmatrix}$$

$\neq 0$ if and only if
eigenvectors are linearly
independent. Which they
will always be in this case

Bottom line: Don't worry about Wronskian!

~~eg~~ (d) Initial condition

will have the form $\vec{x}(0) = \vec{x}_0$

We need:

$$\vec{x}_0 = c_1 \vec{p}^{(1)} + c_2 \vec{p}^{(2)} + \dots + c_n \vec{p}^{(n)}$$

This is the system

$$\begin{pmatrix} | & | & & | \\ \vec{p}^{(1)} & \vec{p}^{(2)} & \dots & \vec{p}^{(n)} \\ | & | & & | \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix} = \vec{x}_0$$

which will always have unique solution.

e.g. 1. $\vec{x}' = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix} \vec{x}$

$$A = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix} \quad A - rI = \begin{pmatrix} 1-r & 1 \\ 4 & 1-r \end{pmatrix}$$

$$\det(A - rI) = \begin{vmatrix} 1-r & 1 \\ 4 & 1-r \end{vmatrix} = (1-r)^2 - 4 = 0$$

$$1-r = \pm 2 \rightarrow \underline{r = -1, r = 3}, \leftarrow \text{eigenvalues.}$$

Eigenvectors:

$\lambda = -1$: Solve $(A + I)\vec{x} = \vec{0}$

$$\begin{pmatrix} 2 & 1 \\ 4 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\left(\begin{array}{cc|c} 2 & 1 & 0 \\ 4 & 2 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 2 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

$$2x_1 + x_2 = 0$$

$$x_2 = t$$

$$x_1 = -\frac{1}{2}t$$

$$\vec{x}(t) = t \begin{pmatrix} -\frac{1}{2} \\ 1 \end{pmatrix}$$

$$t \in \mathbb{R}$$

Take $\vec{x}(1) = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$ (i.e. $t=2$)

$$\underline{\lambda = 3} \quad \left(\begin{array}{cc|c} -2 & 1 & 0 \\ 4 & -2 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} -2 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

$$-2x_1 + x_2 = 0 \rightarrow x_1 = \frac{1}{2}x_2$$

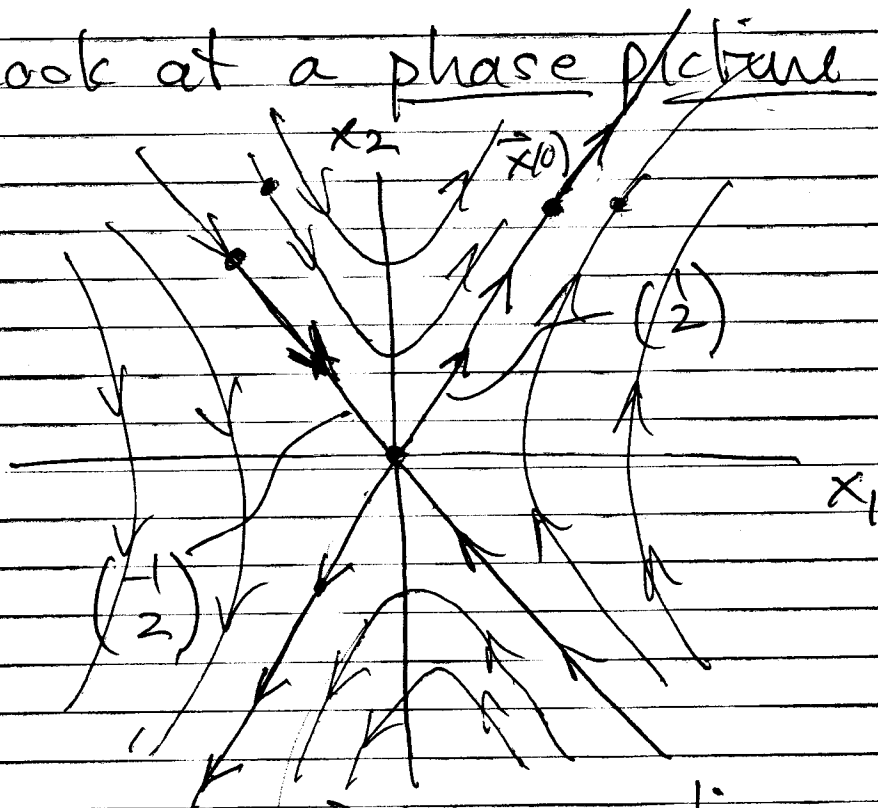
$$x_2 = t$$

$$\vec{x}(2) = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad t=2$$

General solution

$$\vec{x}(t) = c_1 \begin{pmatrix} -1 \\ 2 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{3t} //$$

Look at a phase picture.



Suppose $\vec{x}(0)$ is on line parallel to $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$

$$\vec{x}(0) = \alpha \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad \text{some } \alpha \in \mathbb{R}.$$

To find c_1, c_2 need to solve:

$$\begin{pmatrix} -1 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} \alpha \\ 2\alpha \end{pmatrix} \rightarrow \begin{matrix} c_1 = 0 \\ c_2 = \alpha \end{matrix}$$

$$\text{So } \vec{x}(t) = \alpha \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{3t}$$

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If $\vec{x}(0)$ is on line parallel to $\begin{pmatrix} -1 \\ 2 \end{pmatrix}$

$$\vec{x}(0) = \beta \begin{pmatrix} -1 \\ 2 \end{pmatrix} \quad \begin{pmatrix} -1 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} -\beta \\ 2\beta \end{pmatrix}$$

$$c_2 = 0 \quad c_1 = \beta \quad \vec{x}(t) = \beta \begin{pmatrix} -1 \\ 2 \end{pmatrix} e^{-t}$$

eg #16) $\vec{x}' = \begin{pmatrix} -2 & 1 \\ -5 & 4 \end{pmatrix} \vec{x} \quad \vec{x}(0) = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$

Eigenvalues

$$\begin{vmatrix} -2-r & 1 \\ -5 & 4-r \end{vmatrix} = (-2-r)(4-r) + 5$$

$$= r^2 - 2r - 3 = 0 \quad (r+1)(r-3) = 0$$

$$r = -1, r = 3$$

Eigenvectors:

$$\underline{r = -1} \quad \begin{pmatrix} -1 & 1 & 0 \\ -5 & 5 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} -1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$-x_1 + x_2 = 0$$

$$x_1 = 1$$

$$\vec{v} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$x_2 = 1 \leftarrow \text{arbitrary, } b$$

$$\underline{r=3} \quad \begin{pmatrix} -5 & 1 & 0 \\ -5 & 1 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} -5 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$-5x_1 + x_2 = 0 \quad x_1 = \frac{1}{5}$$

$$x_2 = 1$$

$$\vec{v}(2) = \begin{pmatrix} 1 \\ 5 \end{pmatrix}$$

$$\vec{x} = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 1 \\ 5 \end{pmatrix} e^{3t}$$

Solve

$$\begin{pmatrix} 1 & 1 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix} \quad \begin{array}{l} c_1 + c_2 = 1 \\ -(c_1 + 5c_2 = 3) \end{array}$$

$$-4c_2 = -2$$

$$\vec{x}(t) = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-t} + \frac{1}{2} \begin{pmatrix} 1 \\ 5 \end{pmatrix} e^{3t} //$$

$$c_2 = \frac{1}{2} \quad c_1 = \frac{1}{2}$$

e.g. #18) $\vec{x}' = \begin{pmatrix} 0 & 0 & -1 \\ 2 & 0 & 0 \\ -1 & 2 & 4 \end{pmatrix} \vec{x}$

$$\begin{vmatrix} -r & 0 & -1 \\ 2 & -r & 0 \\ -1 & 2 & 4-r \end{vmatrix} = -r(-r(4-r)) - (4-r) = 0$$

$$(4-r)(r^2-1) = 0 \quad \boxed{r=4, r=1, r=-1}$$

$r=4$ $\frac{1}{4} \begin{pmatrix} -4 & 0 & -1 & 0 \\ 2 & -4 & 0 & 0 \\ -1 & 2 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} -4 & 0 & -1 & 0 \\ 0 & -4 & -1/2 & 0 \\ 0 & 2 & 1/4 & 0 \end{pmatrix}$

$$\rightarrow \begin{pmatrix} -4 & 0 & -1 & 0 \\ 0 & -4 & -1/2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \begin{matrix} x_1 = -1/4 \\ x_2 = -1/8 \\ x_3 = 1 \end{matrix}$$

$$-4x_2 - 1/2 x_3 = 0$$

$$-4x_2 - 1/2 = 0$$

$$x_2 = -1/8$$

$$\vec{y}(t) = \begin{pmatrix} -2 \\ -1 \\ 8 \end{pmatrix}$$

etc....