

Final Exam 12/13 1:30 - 4:15

Information on the final is on website.

Quiz 14 12/8 7.1, 7.3

Goal: Solve $\vec{x}' = A\vec{x}$ A const $n \times n$ matrix

Eigenvalues / Eigenvectors

A : $n \times n$ matrix

λ is an eigenvalue of A if $A\vec{x} = \lambda\vec{x}$ for some non-zero vector \vec{x} . In this case \vec{x} is an eigenvector corresponding to λ .

How do you find eigenvalues / vectors?

$$A\vec{x} = \lambda\vec{x} \iff A\vec{x} - \lambda\vec{x} = \vec{0} \iff (A - \lambda I)\vec{x} = \vec{0}$$

In order for this to have non-zero solution we must have $\boxed{\det(A - \lambda I) = 0}$

e.g. $A = \begin{pmatrix} 3 & -1 \\ 4 & -2 \end{pmatrix}$ Find eigenvalues

$$A - \lambda I = \begin{pmatrix} 3 & -1 \\ 4 & -2 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 3-\lambda & -1 \\ 4 & -2-\lambda \end{pmatrix}$$

$$\det(A - \lambda I) = \begin{vmatrix} 3-\lambda & -1 \\ 4 & -2-\lambda \end{vmatrix} = (3-\lambda)(-2-\lambda) + 4$$

$$= \lambda^2 - \lambda - 2$$

$$\lambda^2 - \lambda - 2 = 0 \rightarrow (\lambda + 1)(\lambda - 2) = 0$$

$$\boxed{\lambda = -1, \lambda = 2}$$

e.g. #22 p 373

$$A = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix} \quad \text{Recall we found eigenvectors}$$

$$\vec{g}(1) = \begin{pmatrix} 4 \\ 2 \end{pmatrix} \quad \vec{g}(2) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

What are the eigenvalues?

$$A \vec{g}(1) = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} 4 \\ 2 \end{pmatrix} = \begin{pmatrix} 8 \\ 4 \end{pmatrix} = 2 \begin{pmatrix} 4 \\ 2 \end{pmatrix} \quad \lambda = 2$$

$$A \vec{g}(2) = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} -1 \\ -2 \end{pmatrix} = (-1) \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad \lambda = -1$$

$$(A - 2I) = \begin{pmatrix} 3-2 & -2 \\ 2 & -2-2 \end{pmatrix} = \begin{pmatrix} 1 & -2 \\ 2 & -4 \end{pmatrix} \quad \det = -4 + 4 = 0$$

$$(A - (-1)I) = \begin{pmatrix} 4 & -2 \\ 2 & -1 \end{pmatrix} \quad \det = -4 + 4 = 0$$

How do you find eigenvectors?

Solve $(A - \lambda I)\vec{x} = \vec{0}$ if λ is an eigenvalue.

e.g. $A = \begin{pmatrix} 3 & -1 \\ 4 & -2 \end{pmatrix}$ $\lambda = 2$
 $\lambda = -1$

$\lambda = 2$: Solve $\begin{pmatrix} 3-2 & -1 \\ 4 & -2-2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\begin{pmatrix} 1 & -1 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 & 0 \\ 4 & -4 & 0 \end{pmatrix} \xrightarrow{\text{Row reduction}} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} x_1 - x_2 = 0 \\ x_1 = t \\ x_2 = t \end{array}$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} t \\ t \end{pmatrix} = t \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad t \in \mathbb{R}.$$

$\lambda = -1$ Solve $\begin{pmatrix} 4 & -1 \\ 4 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$4x_1 - x_2 = 0 \quad x_1 = \frac{1}{4}t \quad \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = t \begin{pmatrix} \frac{1}{4} \\ 1 \end{pmatrix} \quad t \in \mathbb{R},$$

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or could say $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = s \begin{pmatrix} 1 \\ 4 \end{pmatrix}, s \in \mathbb{R}$

eg #25) $A = \begin{pmatrix} 3 & 2 & -4 \\ 2 & 0 & 2 \\ 4 & 2 & -3 \end{pmatrix}$

$$\det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 2 & -4 \\ 2 & -\lambda & 2 \\ 4 & 2 & 3+\lambda \end{vmatrix}$$

$$= (3-\lambda)[(-\lambda)(3-\lambda)-4] - 2[2(3-\lambda)-8]$$

$$+ 4[4 + 4(\lambda)]$$

$$= (3-\lambda)[\lambda(\lambda-3)-4] - 4[3-\lambda-4-4-4\lambda]$$

$$= (3-\lambda)[\lambda^2-3\lambda-4] - 4[-5\lambda-5]$$

$$= (3-\lambda)(\lambda+1)(\lambda-4) + (4)(5)(\lambda+1)$$

$$= (\lambda+1)((3-\lambda)(\lambda-4) + 20)$$

$$= (\lambda+1)(-\lambda^2 + 7\lambda + 8)$$

$$= -(\lambda+1)(\lambda^2 - 7\lambda - 8) = -(\lambda+1)(\lambda+1)(\lambda-8)$$

Eigenvalues $\lambda = -1, \lambda = 8$

Note: A is 3×3 but we only get 2 eigenvalues

$\lambda = -1$: Solve $(A - \lambda I)\vec{x} = \vec{0}$

$$\begin{pmatrix} 4 & 2 & 4 & 0 \\ 2 & 1 & 2 & 0 \\ 4 & 2 & -4 & 0 \end{pmatrix} \xrightarrow{\text{G.E.}} \begin{pmatrix} 4 & 2 & 4 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

or reduces to one equation: $2x_1 + x_2 + 2x_3 = 0$

$$x_1 = -\frac{1}{2}s - t$$

$$x_2 = s$$

$$x_3 = t$$

$$2x_1 = -x_2 - 2x_3$$

$$x_1 = -\frac{1}{2}x_2 - x_3$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = s \begin{pmatrix} -\frac{1}{2} \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

two linearly independent eigenvectors for $\lambda = -1$;
e.g. $\begin{pmatrix} -1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$

$$\begin{aligned} \underline{\lambda = 8}: & \quad \begin{pmatrix} -5 & 2 & 4 & 0 \\ 2 & -8 & 2 & 0 \\ 4 & 2 & -5 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} -5 & 2 & 4 & 0 \\ 0 & -\frac{36}{5} & \frac{18}{5} & 0 \\ 0 & \cancel{\frac{18}{5}} & -\frac{9}{5} & 0 \end{pmatrix} \\ & \rightarrow \begin{pmatrix} -5 & 2 & 4 & 0 \\ 0 & -\frac{36}{5} & \frac{18}{5} & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} x_1 &= \frac{3}{5}t & -2x_2 + x_3 &= 0 \\ x_2 &= -\frac{1}{2}t & -5x_1 + 2x_2 + 4x_3 &= 0 \\ x_3 &= t & -5x_1 - t + 4t &= 0 \\ & & -5x_1 + 3t &= 0 \end{aligned}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = t \begin{pmatrix} 3/5 \\ -1/2 \\ -1 \end{pmatrix}, \quad t \in \mathbb{R}.$$

7.4 Basic Theory of 1st order linear systems.

Recall basic theory of nth order linear homogeneous equations.

$$y^{(n)} + p_1 y^{(n-1)} + \dots + p_n y = 0$$

1. Try to find n solutions, $y_1, y_2, y_3, \dots, y_n$ in some way. Are they a fundamental set of solutions? Compute Wronskian:

$$W(y_1, y_2, \dots, y_n) = \begin{vmatrix} y_1 & y_2 & \dots & y_n \\ y_1' & y_2' & \dots & y_n' \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n)} & y_2^{(n)} & \dots & y_n^{(n)} \end{vmatrix}$$

determinant
 $\neq 0$ for all t?

2. Any solution can be written uniquely as

$$\varphi(t) = c_1 y_1(t) + c_2 y_2(t) + \dots + c_n y_n(t)$$

3. If the coefficients P_1, P_2, \dots, P_n are constant then we can always find n solutions by solving characteristic equation. They will automatically be a fundamental set.

1st order linear systems.

$$\vec{x}'(t) = P(t)\vec{x}(t) + \vec{g}(t)$$

$$\vec{x}(t) = \begin{pmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{pmatrix} \quad P(t) = \begin{pmatrix} P_{11}(t) & P_{12}(t) & \cdots & P_{1n}(t) \\ \vdots & \vdots & \ddots & \vdots \\ P_{n1}(t) & P_{n2}(t) & \cdots & P_{nn}(t) \end{pmatrix}$$

$$\vec{g}(t) = \begin{pmatrix} g_1(t) \\ \vdots \\ g_n(t) \end{pmatrix} \quad \vec{g}(t) = 0 \text{ means system is } \underline{\text{homogeneous}}.$$

1. Want to find n solutions.

e.g. $\vec{x}'(t) = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix} \vec{x}(t)$

$$\rightarrow \vec{x}(t) = c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{3t} + c_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{2t}$$

Would write

$$\vec{x}^{(1)}(t) = \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{-t} = \begin{pmatrix} e^{-t} \\ 2e^{-t} \end{pmatrix}$$

$$\vec{x}^{(2)}(t) = \begin{pmatrix} 1 \\ \frac{1}{2} \end{pmatrix} e^{2t} = \begin{pmatrix} e^{2t} \\ \frac{1}{2} e^{2t} \end{pmatrix}$$

Check Wronskian:

$$\begin{vmatrix} e^{-t} & e^{2t} \\ 2e^{-t} & \frac{1}{2} e^{2t} \end{vmatrix} = \frac{1}{2} e^t - 2e^{-t} = -\frac{3}{2} e^t \neq 0.$$

In general: Would get

$$\vec{x}^{(1)}(t) = \begin{pmatrix} x_{11}(t) \\ \vdots \\ x_{n1}(t) \end{pmatrix}, \vec{x}^{(2)}(t) = \begin{pmatrix} x_{12}(t) \\ \vdots \\ x_{n2}(t) \end{pmatrix}, \dots, \vec{x}^{(n)}(t) = \begin{pmatrix} x_{1n}(t) \\ \vdots \\ x_{nn}(t) \end{pmatrix}$$

To check linear independence, I form

$$\Sigma(t) = \begin{pmatrix} 1 & & & 1 \\ \vec{x}^{(1)} & \vec{x}^{(2)} & \cdots & \vec{x}^{(n)} \\ 1 & 1 & \cdots & 1 \end{pmatrix}$$

$\{\vec{x}^{(1)}, \dots, \vec{x}^{(n)}\}$ form a fundamental set

If $\det X(t) \neq 0$ for all t on which solution is defined.

Define $W[\vec{x}^{(1)}, \dots, \vec{x}^{(n)}] = \det X(t)$.

In fact, W is either identically zero or never zero.

2. Any solution to $\vec{x}' = P(t)\vec{x}$ can be written uniquely as

$$\vec{\varphi}(t) = c_1 \vec{x}^{(1)}(t) + \dots + c_n \vec{x}^{(n)}(t).$$

vector $\vec{c} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$ depends on initial cond.

3. We will give a method to always find a fund. set. in the case of constant coefficients.