Department of Mathematical Sciences

Ordinary Differential Equations Preliminary Exam

This exam consists of 4 questions.

(1) Consider the linear planar system $\dot{x} = Ax$ for the parameter-dependent matrix

$$A = \left[\begin{array}{cc} \alpha & 1 \\ 1 & \alpha \end{array} \right] , \quad \alpha \in \mathbb{R} .$$

- (a) For which values of α is the origin of this system stable, for which values is it a saddle?
- (b) For the case $\alpha = -5$, let $(x_1(t), x_2(t))$ be a nontrivial solution of the above linear system with the initial value $(x_1(0), x_2(0)) = (a, b) \neq (0, 0)$. Find all possible values of $\lim_{t\to\infty} x_2(t)/x_1(t)$. Which initial conditions (a, b) lead to which limit?
- (2) Let $g: \mathbb{R} \to \mathbb{R}$ be a continuously differentiable function, and consider the planar system

$$\dot{x} = -yg(x^2 + y^2)$$

 $\dot{y} = xg(x^2 + y^2)$.

- (a) Transform the system into polar coordinates.
- (b) If the function g has no zero, sketch all possible phase portraits.
- (c) For $g(\rho) = \rho 1$, sketch the phase portrait, find all possible equilibria, and determine their stability.
- (3) Consider the planar system

$$\dot{x} = 10 - x - \frac{4xy}{1 + x^2}$$
$$\dot{y} = 3x \left(1 - \frac{y}{1 + x^2}\right)$$

- (a) Find the unique equilibrium solution and show that it is unique.
- (b) Show that the rectangle $R = \{(x, y) \in \mathbb{R}^2 : 0 < x < 10, 0 < y < 101\}$ is positively invariant. (You may use without proof that solutions cannot escape through the four corners of R.)
- (c) Using the fact that the equilibrium from part (a) is repelling (you do not have to verify this), show that there is a periodic orbit in R.
- (4) Consider the planar system

$$\dot{x} = -x + 2xy^2 \dot{y} = xy + x^2y .$$

- (a) Find all equilibrium solutions. Which invariant manifolds exist for the equilibria on the y-axis?
- (b) Describe the phase portrait in a neighborhood of (0,0) as precisely as possible. In particular, what are the possible ω -limit sets of orbits starting near (0,0)? (Hint: Linearize about (0,0), and use the generalized Hartman-Grobman Theorem.)